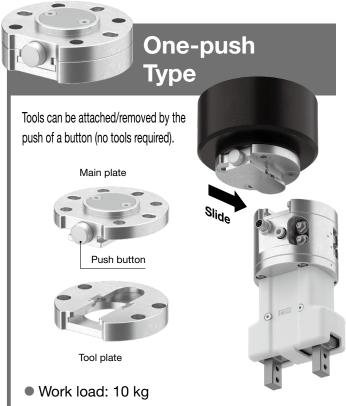
Tool Changer One-push Type/Clamp Type



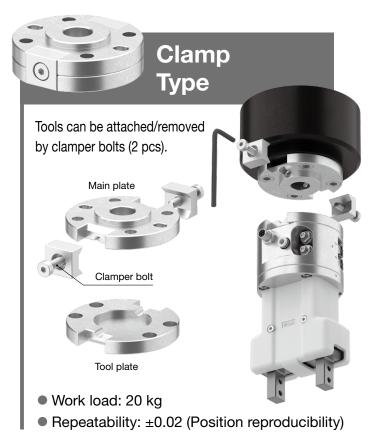
2 types of manual tool changers



Repeatability: ±0.01 (Position reproducibility)

Allows for the easy manual exchange of robot hand tools





Standards: ISO9409-1-50-4-M6 compliant

Compatible with the flanges of most major collaborative robots





Compact, Lightweight

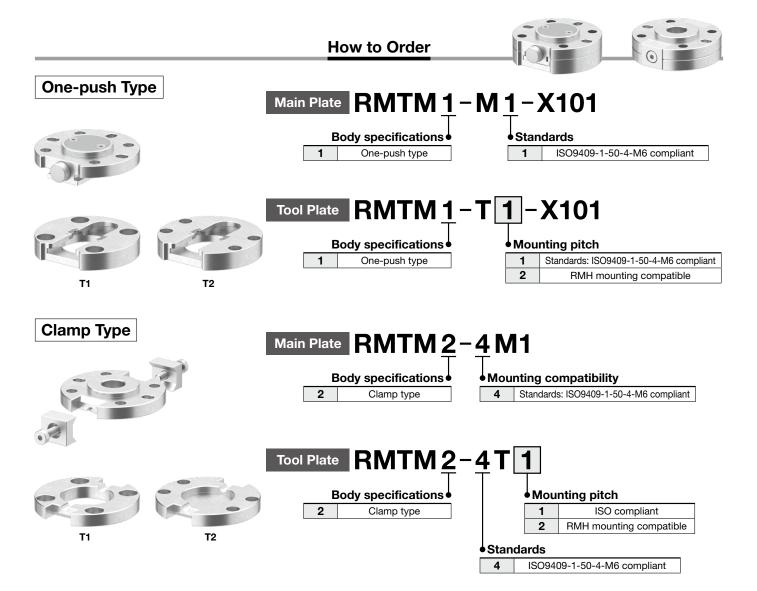
Туре	Height	Weight	
One-push type	18.5 mm	137 g*1	Height
Clamp type	16 mm	137 g*1	

*1 The weight of the mounting bolts and positioning pins is not included.



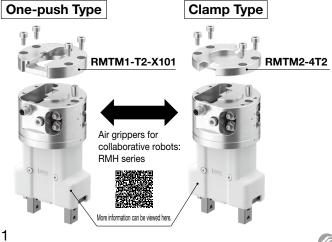
RMTM Series

Tool Changer One-push Type/Clamp Type **RMTM Series**



RMH Mounting Compatible Option (Tool Plate)

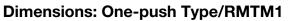
Tool plate that can be mounted on RMH series air grippers for collaborative robots Select when changing between the clamp type and the one-push type.

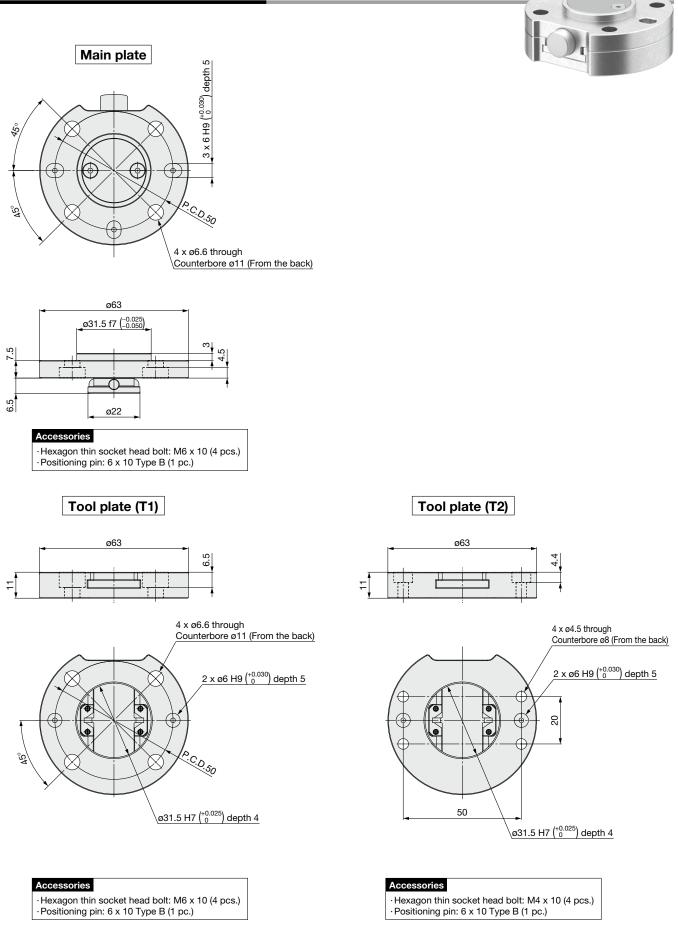


Specifications

Model		RMTM1 (One-push type)	RMTM2 (Clamp type)
Work load		10 kg	20 kg
Repeatability (Position reproducibility)		±0.01	±0.02
	Main plate	84 g	99 g
Weight	Tool plate (T1)	53 g	38 g
	Tool plate (T2)	58 g	44 g
Moment resistance		20 N·m	60 N·m
Torque resistance		20 N·m	60 N⋅m
Standards		ISO9409-1-50-4-M6	ISO9409-1-50-4-M6
Recommended connection torque		_	2.7 to 3.3 N·m
Operating temperature range		0 to 60°C (No freezing)	0 to 60°C (No freezing)

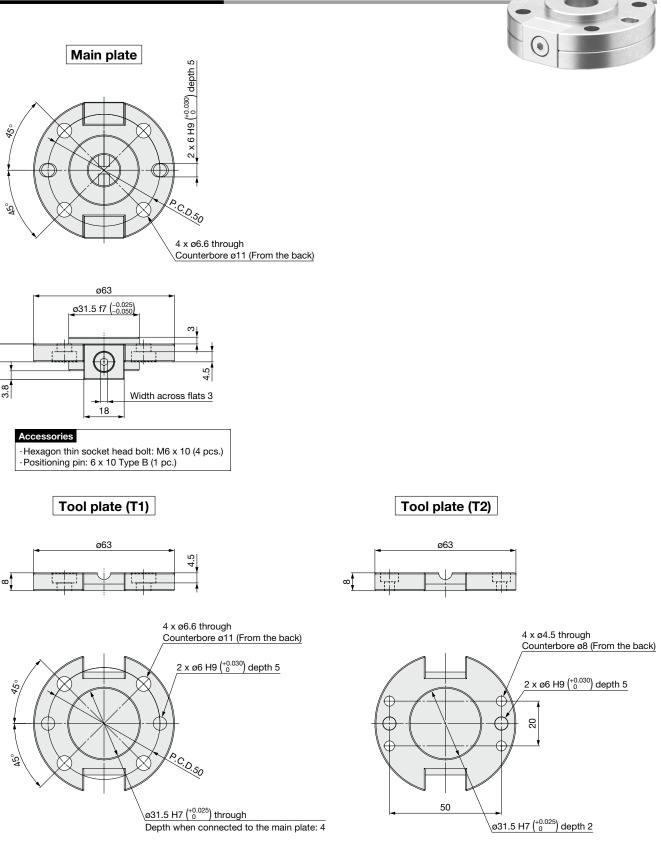
Tool Changer **RMTM** Series





RMTM Series

Dimensions: Clamp Type/RMTM2



Accessories

· Hexagon thin socket head bolt: M6 x 10 (4 pcs.) · Positioning pin: 6 x 10 Type B (1 pc.) Accessories

Hexagon thin socket head bolt: M4 x 8 (4 pcs.)

• Positioning pin: 6 x 10 Type B (1 pc.)

15.8 8 15.8



RMTM Series Specific Product Precautions

Be sure to read this before handling the products. For safety instructions as well as air gripper and auto switch precautions, refer to the "Handling Precautions for SMC Products" and the "Operation Manual" on the SMC website: https://www.smcworld.com

Connection and Disconnection Procedures (One-push Type)

1. Connection/disconnection is possible by sliding the tool plate while pushing down on the push button.







Connection and Disconnection Procedures (Clamp Type)

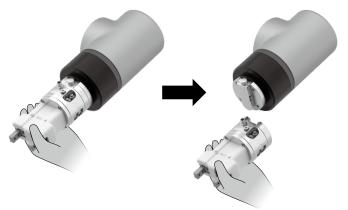
1. Disconnection is possible by loosening the bolts that secure the clampers in place on both sides. When connecting, align the clampers with the grooves in the tool plate, and tighten the bolts on both sides.



Safety Instructions (One-push Type)

1. Depending on the robot's positioning, the tool may slide out under its own weight when the button is pushed.

Therefore, when exchanging tools, take note of the robot's positioning, and support the tool to be removed with your hands if needed.



2. Confirm that the push button has returned to its original height and that the tool plate is securely locked in place. If locking is insufficient, dropping of the tool or workpiece may result.

A Safety Instructions Be sure to read the "Handling Precautions for SMC Products" (M-E03-3) and "Operation Manual" before use.

SMC Corporation https://www.smcworld.com