# Vacuum Manifold for Fieldbus System







Vacuum Unit/Positive Pressure Unit

# Vacuum pads and actuator driving can be controlled with a single manifold



### 5-port solenoid valve

- 2-position single
- 2-position double
- 4-position dual 3-port valve

# Vacuum unit

#### **Energy saving ejector**





Reduced by the energy saving SI unit, built-in pressure sensor, and efficient ejectors

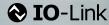
(Under SMC's measurement conditions)



# Fieldbus compatible

- Space saving: Requires no separate input/ output units
- Reduced wiring time
- Compatible protocols





EtherNet/IP EtherCAT

# Exhaust sealing function p. 4



Quick workpiece release

4 stations/8 stations/12 stations/ 16 stations manifold compatible







# **Energy saving**

Air saving by the energy saving SI unit, built-in pressure sensor, and efficient ejectors

CO<sub>2</sub> emissions (Air consumption)

92% reduction

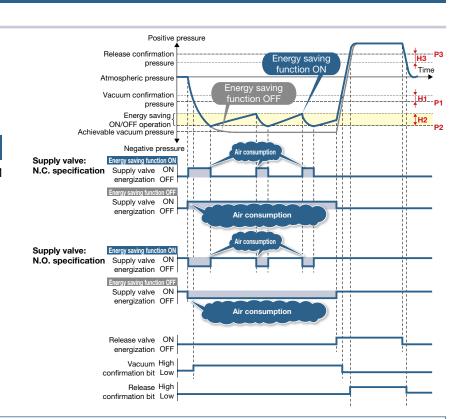
\*1 Under SMC's measurement conditions

#### Energy saving function ON

Air is supplied **intermittently** when the vacuum decreases.

#### Energy saving function OFF

Air is supplied **continuously** during the adsorption of the workpiece.



# Energy saving efficiency: 92% reduction

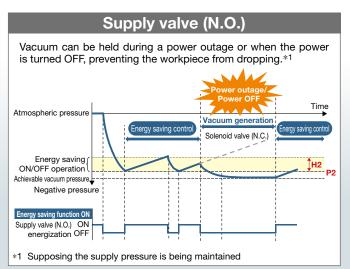
Power consumption cost per year reduced

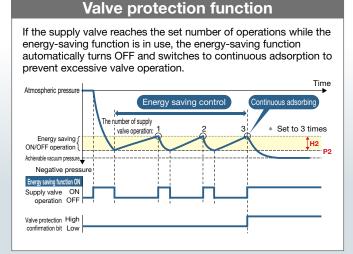
by **13,196** JPY/year\*2

	Power consumption cost per year	Annual air consumption	Exhaust time	Air consumption
ZKJ/Energy saving function ON (Part no.: ZKJ12C8P-A5U-T1)	1,148 JPY/year	765 m³/year	0.6 s	68 L/min
Existing model (Part no.: ZM131AM-K5LZ-E15)	14,344 JPY/year	9562.5 m³/year	6 s	85 L/min

\*2 Cost conditions

Air unit 1.5 JPY/m³ (ANR), Annual operating cycles: 1125000 (Operating hours: 10 hours/day, Operating days: 250 days/year, 450 cycles/h, when 1 unit is used)





With energy

saving function

More efficient

ejector

# Fieldbus Compatible

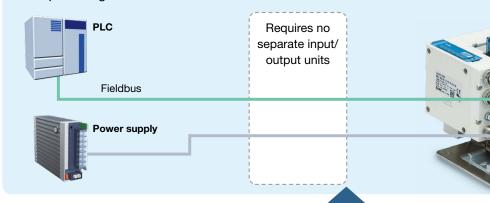


EtherNet/IP EtherCAT

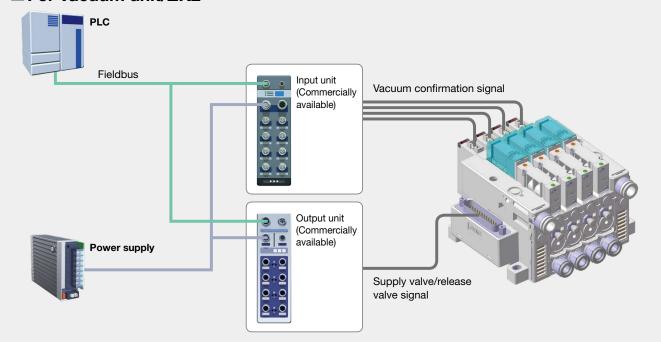
# Space saving/Less wiring work

#### For vacuum manifold for fieldbus system/ZKJ

- Can be connected directly to the PLC via Fieldbus without the need for a commercially available input/output unit
- Less communication/power supply cables and wiring work
- Reduced network load due to the reduction in the number of connected devices
- Simple wiring/Minimized disconnection risk



#### For vacuum unit/ZK2



# Remote control and monitoring are available.



Fieldbus

#### Configurable items

- Energy saving function
- Pressure value (vacuum confirmation (P1, H1), energy saving operation threshold (P2, H2), release confirmation (P3, H3))

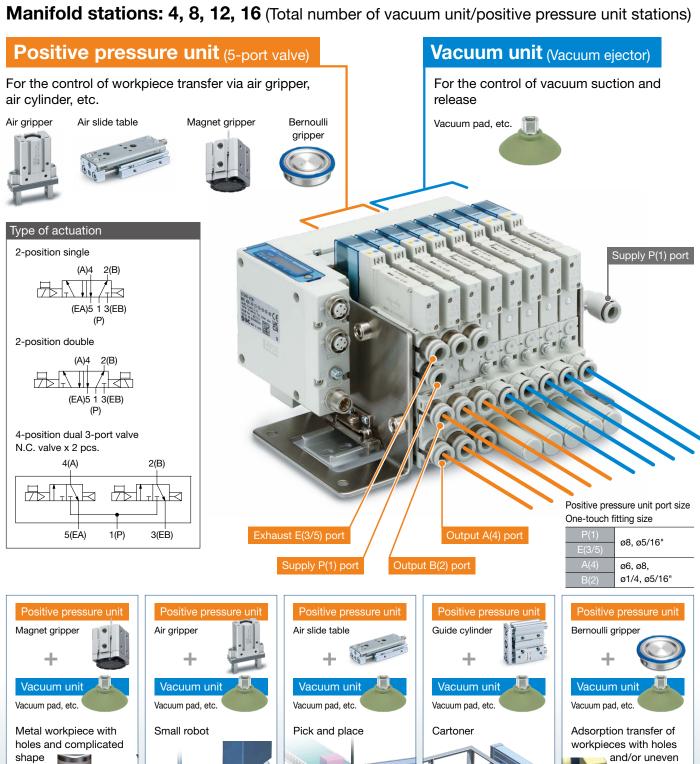
Monitoring

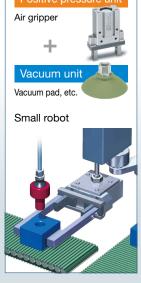
Monitoring pressure of individual vacuum units



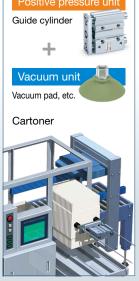
# Vacuum ejectors and solenoid valves are mounted on the same manifold.

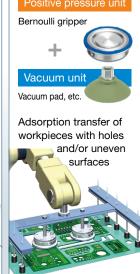
This allows for a compact body and reduced wiring/wiring labor.











### **Variations**

#### SI unit/Compatible protocols





EtherNet/IP EtherCAT.

#### Nozzle size

ø0.7, ø1.0, ø1.2, ø1.5

#### Combination of supply valve and release valve

Supply valve	Release valve
N.O.	N.C.
N.C.	N.C.

#### Supply valve: N.O. specification available

- Can hold vacuum\*1 even when the power goes out or is turned off
- Prevents the sudden dropping of workpieces\*1
- \*1 Supposing the supply pressure is being maintained

#### Manual override for residual pressure release (Option)

Without manual override: Plug

Allows for manual vacuum release With manual override (Non-locking push type): Red





#### Air pressure supply (P) port

ø8, ø5/16" One-touch fittings

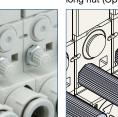
#### Air pressure supply (P) port

· With One-touch fitting When operating ejectors simultaneously, if the flow rate from a single air pressure supply (P) port is insufficient, it is possible to select one with a fitting. (Refer to the "Max. Number of Manifold Stations that Can Operate Simultaneously" on page 16.)

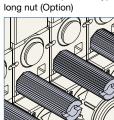
· None: Plug

# Vacuum release flow adjusting needle

Manual override type



Screwdriver operation type



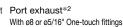
# Exhaust (EXH) port

 $\label{eq:high-noise} \textit{High-noise reduction silencer exhaust} \quad \textit{Port exhaust} \\ ^{*2}$ (Exhaust noise: 52 [dB(A)])\*1



Unpleasant frequencies are removed while maximizing vacuum performance by using a dedicated silencer with better silencing effect

\*1 Adsorbs the workpiece (nozzle diameter ø0.7 (1 station)). (Under SMC's measurement conditions)

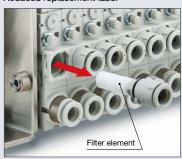




\*2 For positive pressure units, only port exhaust is available.

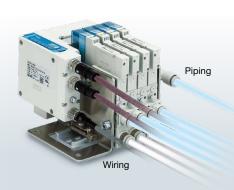
#### Vacuum (V) port

ø6, ø8, ø1/4", ø5/16" One-touch fittings Built-in filter: No tools are required. Reduced replacement labor



The vacuum port is located above the exhaust port. The location is different from that of the ZK2 series.

#### Wiring and piping are integrated on one side.



#### **Exhaust sealing function**

The built-in exhaust sealing valve seals release air to prevent it from being exhausted from the exhaust (EXH) port. Improved workpiece release

Vacuum release flow rate increased by 2 times (Under SMC's measurement conditions) High release pressure allows for the quick release of workpieces.

High-noise reduction silencer exhaust ⊢∏⊅EXH Exhaust sealing valve Port exhaust -⊳EXH

For the type with an exhaust sealing valve, high vacuum release pressure allows for the quick release of workpieces.





# **PROFINET Compatible**

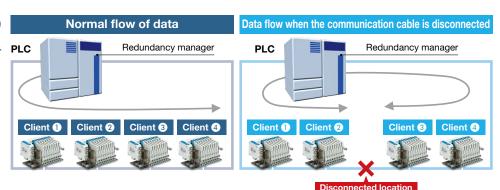


### **MRP/MRPD** function

# MRP (Media Redundancy Protocol) function

Communication can be continued even if one of the communication cables in the network is disconnected or damaged. Furthermore, as it is possible to identify the disconnection point quickly, the network disconnection time can be kept within 200 ms.

\* In order to use the MRP function, the PLC must be able to support it.



#### MRPD (Media Redundancy for planned duplication)

It is possible to duplicate routes with a ring topology configured with PROFINET IRT communication.

Communication reconnection time is faster than with the MRP function, so communication can be continued without recovery time.

# **Fast Start Up function**

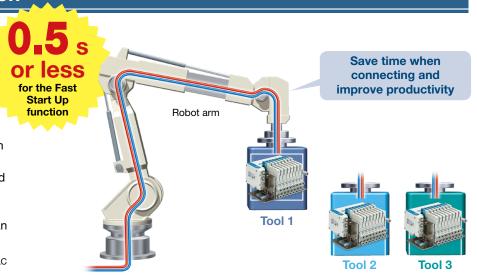
Time from power ON to communication connection:

# Approx. 10 s

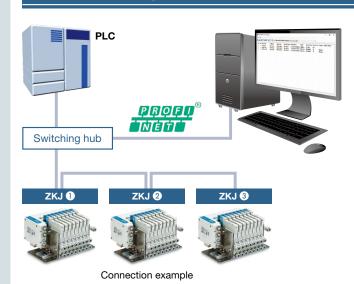
In the case of a tool changer, it takes about 10 seconds for communication to be connected in some products after the power to the device installed on the tool is turned ON.

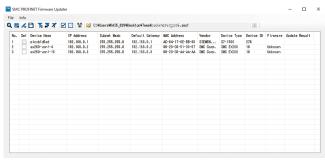
For products which support the Fast Start Up function, communication can be operational even faster.

\* In order to use the Fast Start Up function, the PLC must be able to support it.



# FW (firmware) updates





- Batch firmware updating for up to 255 units is possible from the Ethernet line.
- Easy to handle future version upgrades
- \* Depending on the product's hardware and firmware versions, it may not be possible to use the firmware update function.

# **PROFINET Compatible**



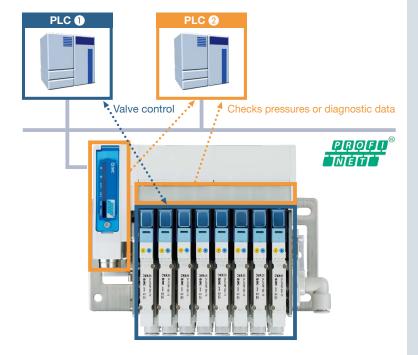
# **Shared Device function**

An I/O data connected to an SI unit can be controlled and checked by multiple I/O controllers (PLC).



Ex. PLC1 controls the valve

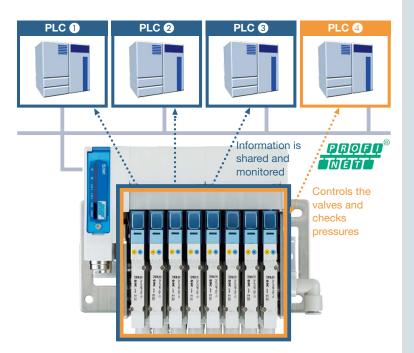
PLC2 checks pressures or diagnostic data



- Information can be shared with up to 3 controllers in addition to the control PLC.
- The cost of the hardware, cables, and installation space can be reduced.

Ex. Information of PLC4 is shared and monitored by PLC1 to 3.

PLC4 controls the valves and checks pressures.



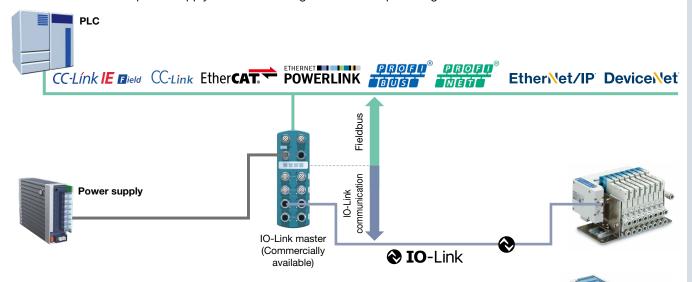
\* The Shared Device function enables an I/O module connected to the I/O device to be controlled by multiple I/O controllers (PLC). The control status can be shared among other I/O controllers. As the function can be used across the entire PROFINET line, the cost for hardware, cables, and installation space can



# IO-Link Compatible @ IO-Link

# Space saving/Less wiring work

- Requires no separate input/output units
- Connectable to various networks via an IO-Link master (Communication is possible without reliance on a Fieldbus or PLC.)
- Less communication/power supply cables and wiring work
- Reduced wiring space
- Reduced network load due to the reduction in the number of Fieldbus connected devices
- Simple wiring/Minimized disconnection risk



# Connectable with a single general-purpose cable

#### Port class B

supply load

supply load

IO-Link master (Commercially available)

- Connect the IO-Link master port to the device using a 1:1 configuration.
- Connect using an M12 connector.
- Maximum cable length: 20 m

**IO**-Link

• Special communication cables are not necessary.

\* In order to connect the SI unit using a single cable, use a port class B type IO-Link master.

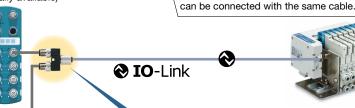


Port class B compliant

#### Port class A

IO-Link master (Commercially available) General-purpose 5-wire unshielded cables are used for connection.

The signal wire and valve power supply wire



#### SI unit/Connector pin arrangement

Pin no.	SI unit port pin function (Port class B)
1	+24 V for control and input
2	+24 V for output
3	0 V for control and input
4	IO-Link communication
5	0 V for output

# Difference between IO-Link master port class A and class B

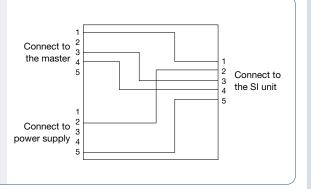
-	master port class A and class B								
	Pin	IO-Link master port pin function							
	no.	Port class A	Port class B						
	1	+24 V	+24 V						
	2	NC/DI/DO	Additional power supply +24 V						
	3	0 V	0 V						
	4	IO-Link/DI/DO	IO-Link/DI/DO						
	5	NC	Additional power supply 0 V						

# Port class A compliant A special wiring Y branch connector is available.

Y Branch Connector

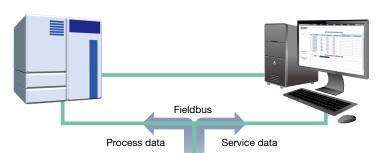


Used when connecting to a port class A type IO-Link master, which is often used when connecting to an IO-Link sensor



# IO-Link Compatible IO-Link

# Self-diagnosis function/Automatic parameter saving and writing



0-0

O.-.C

IO-Link master

(Commercially available)

#### Self-diagnosis contents (Examples)

Diagnostic contents	Event category
Internal failure of the SI unit	Error
Vacuum unit valve short circuit	Error
Pressure sensor short circuit	Error
Pressure sensor failure/disconnection	Error
Voltage drop of power supply for logic/input	Warning
Valve protection function in use	Warning

# Real-time diagnosis (Process data)

- · Any event information detected by the SI unit using the process data can be transmitted to the PLC and PC in real time via the upper level Fieldbus.
- · 2 types of event flags are transmitted to the PLC and PC. (Error/Warning)

# Request base diagnosis (Service data)

 Regarding detailed diagnostic information, the event codes can be transmitted as service data to the PLC and PC.

**O**IO-Link

#### **Data storage function**

- The parameters of each ejector can be saved automatically to the IO-Link master.
- When replacing or adding an IO-Link device, the saved parameters can be written automatically, reducing replacement/setup time.



#### Implement diagnostic bits in the process data.

The diagnostic bit in the cyclic process data makes it easy to find problems with the equipment. It is possible to find problems with the equipment in real time using the cyclic (periodic) data and to monitor such problems in detail with the noncyclic (aperiodic) data.

#### **Process Data**

Vacuum manifold stations	Input process data	Output process data
4	4 byte	2 byte
8	5 byte	3 byte
12	6 byte	4 byte
16	7 byte	5 byte

\* The process data size occupied by the SI unit depends on the number of vacuum manifold stations.

	nput	process	data
--	------	---------	------

Byte	1						0									
Bit offset	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Item								Pressur	e value							
Byte	te 3									2	2					
Bit offset	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
Item	CH3 Release confirmation	CH3 Vacuum confirmation	CH2 Release confirmation	CH2 Vacuum confirmation	CH1 Release confirmation	CH1 Vacuum confirmation	CH0 Release confirmation	CH0 Vacuum confirmation	Valve protection	Parameter setting error	Supply valve setting mismatch			Pressure sensor failure/ disconnection	Pressure sensor short circuit	Valve short circuit
Byte				Ę	5				4							
Bit offset	47	46		44	43	42	41	40	39	38	37	36	35	34	33	32
Item	CH11 Release confirmation	CH11 Vacuum confirmation	CH10 Release confirmation	CH10 Vacuum confirmation	CH9 Release confirmation	CH9 Vacuum confirmation	CH8 Release confirmation	CH8 Vacuum confirmation	CH7 Release confirmation	CH7 Vacuum confirmation	CH6 Release confirmation	CH6 Vacuum confirmation	CH5 Release confirmation	CH5 Vacuum confirmation	CH4 Release confirmation	CH4 Vacuum confirmation
Byte	1											(	5			
Bit offset									55	54	53	52	51	50	49	48
Item									CH15 Release confirmation	CH15 Vacuum confirmation	CH14 Release confirmation	CH14 Vacuum confirmation	CH13 Release confirmation	CH13 Vacuum confirmation	CH12 Release confirmation	CH12 Vacuum confirmation

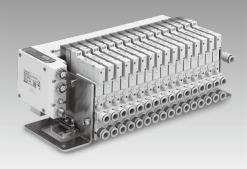
 $\ast\,$  The pressure value of the monitoring channel selected in the output process data can be checked.

#### Output process data

Byte	Byte 1															
Bit offset	15		13	12	11	10	9	8		6	5	4	3	2	1	0
Item	CH3 Release instruction	CH3 Vacuum instruction	CH2 Release instruction	CH2 Vacuum instruction	CH1 CH1 CH0 CH0 n Release Vacuum Release Vacuum Pressure value monitoring channel selection instruction instruction instruction											
Byte				3	3							2	2			
Bit offset	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
Item	CH11 Release instruction	CH11 Vacuum instruction	CH10 Release instruction	CH10 Vacuum instruction	CH9 Release instruction	CH9 Vacuum instruction	CH8 Release instruction	CH8 Vacuum instruction	CH7 Release instruction	CH7 Vacuum instruction	CH6 Release instruction	CH6 Vacuum instruction	CH5 Release instruction	CH5 Vacuum instruction	CH4 Release instruction	CH4 Vacuum instruction
Byte	1											4	4			
Bit offset									39	38	37	36	35	34	33	32
Item									CH15 Release instruction	CH15 Vacuum instruction	CH14 Release instruction	CH14 Vacuum instruction	CH13 Release instruction	CH13 Vacuum instruction	CH12 Release instruction	CH12 Vacuum instruction

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# Vacuum Manifold for Fieldbus System *ZKJ* Series







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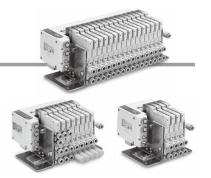
# Vacuum Manifold for Fieldbus System

# ZKJ Series (€ ĽK



#### **How to Order (Manifold)**





#### Manifold stations

Symbol	Manifold stations	Individual unit stations
04	4	Max. 4 stations
08	8	Max. 8 stations
12	12	Max. 12 stations
16	16	Max. 16 stations

- The product outline is every four stations manifold. Be sure that the total number of vacuum units, positive pressure units, and blanking plates is equal to the manifold stations.
- The manifold model number cannot be ordered alone.

Example 1: Only vacuum units

\* Each blanking plate can be replaced with a vacuum unit/ positive pressure unit later in order to increase the number of stations. In addition, the number of stations can be decreased in the same manner for maintenance, etc.

#### 2 SI unit specifications

Symbol	Protocol
DAN	EtherCAT
EAN	EtherNet/IP <sup>TM</sup>
FAN	PROFINET
KAN	IO-Link

#### 3 U-side end plate and supply (P) port

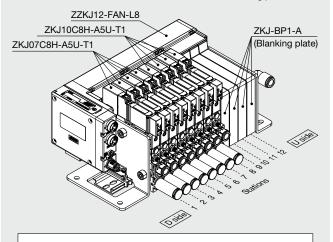
Symbol Supply (P) port  L8 Ø8 Elbow One-touch fittings	

# 

This product cannot be ordered only with the manifold part number. Under the manifold part number, be sure to add the single unit part number (pages 12 and 13) with an asterisk prefix.

### **Ordering Example**

· When 8 vacuum unit stations are required or when an increase to 9 to 12 units may be required in the future due to a change in application, select the 12-station manifold and order 4 sets of blanking plates.



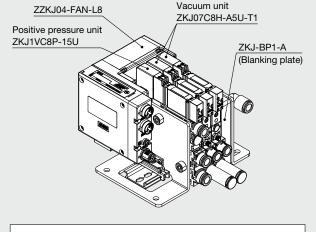
ZZKJ12-FAN-L8 ..... 1 set (Manifold part number) \* ZKJ07C8H-A5U-T1 ······ 4 sets (Vacuum unit)

\* ZKJ10C8H-A5U-T1 ..... 4 sets (Vacuum unit) ZKJ-BP1-A ..... 4 sets (Blanking plate)

The asterisk denotes the symbol for the assembly. Prefix to the single unit part number.

#### Example 2: Mixed vacuum units and positive pressure units

· When 1 positive pressure unit and 2 vacuum units are required, select the 4-station manifold and order 1 set of blanking plates.

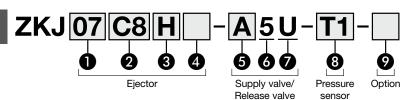


- ZZKJ04-FAN-L8 ...... 1 set (Manifold part number) \* ZKJ1VC8P-15U ..... 1 set (Positive pressure unit)
- \* ZKJ07C8H-A5U-T1 ..... 2 sets (Vacuum unit) ZKJ-BP1-A ..... 1 set (Blanking plate)
- The asterisk denotes the symbol for the assembly. Prefix to the single unit part number.
- · When the manifold is viewed from V port, the first station starts from the left (D side).
- · After the manifold part number, specify the installed single unit from the first station.
- · Please refer to Manifold Options on page 27 for details of the blanking plate.

### How to Order (Single unit for manifold)



## Vacuum unit (Ejector)



#### Nominal nozzle size

<u> </u>	
Symbol Nominal nozzle size	
07	ø0.7
10	ø1.0
12	ø1.2
15	ø1.5

#### 2 Vacuum (V) port, supply (P) port

Symbol	Standard	Vacuum (V) port	Supply (P) port
C6	Metric	ø6	
C8	Metric	ø8	Dlug
N7	Inch	ø1/4"	Plug
N9	IIICII	ø5/16"	
C6U	Metric	ø6	ø6*1
C8U	Metric	ø8	<i>9</i> 0 · ·
N7U	Inch	ø1/4"	ø1/4"* <sup>1</sup>
N9U	IIICII	ø5/16"	91/4

\*1 Select this option when selecting the plug for individual supply option or when increasing the flow rate from the supply port.

### 3 Exhaust (EXH) port

Symbol	Exhaust type
Н	High-noise reduction silencer exhaust
Р	Port exhaust*1

\*1 Port size of exhaust port; mm: ø8, inch: ø5/16"

#### 4 Exhaust sealing valve

	Symbol	Specification
Nil		None
	٧	Exhaust sealing valve

When "15" is selected for the nominal nozzle size, leave the symbol for the exhaust sealing valve blank.

# 5 Combination of supply valve and release valve

Symbol	Supply valve	Release valve
Α	N.C.	N.C.
E	N.O.	N.C.

Check the SI unit supply valve factory settings, and change the SI unit settings in accordance with the selected supply valve.

## 6 Rated voltage

Symbol	Voltage
5	24 VDC

# Light/surge voltage suppressor and common specification

<u>.</u>				
	Symbol	With light	Surge voltage suppressor	Common specification
	U	Yes	Yes	Non-polar

#### Pressure sensor

Symbol	Specifications
T1	-100 to 100 [kPa]
T2	-100 to 200 [kPa]

- \* When "Nil" is selected for 4 exhaust sealing valve, T1 is required. When "V" is selected, T2 is required.
- \* The SI unit pressure sensor is set to T1 (-100 to 100 [kPa]) at the time of shipment. Change the SI unit settings in accordance with the specifications of the selected pressure sensor.

#### Option\*1

<u> </u>	y opinon		
Symbol	Туре		
Nil	Without option		
E	Vacuum release flow adjusting needle screwdriver operation type long lock nut		
М	Plug for individual supply*2, *3 (Blocking the air supply passage to the D side)		
R	With manual override for residual pressure release*4		
Y	Vacuum (V) port release to atmosphere type (Check valve: 1 pc.)*5		

- \*1 When more than one option is selected, list the option symbols in alphabetical order. (Example -EM)
- \*2 The supply (P) port for vacuum manifold is mounted only on the U side. When a vacuum unit/positive pressure unit with a built-in plug for individual supply is selected, be sure to select a supply (P) port via ② for the unit immediately to the D side of the aforementioned unit. For detail, refer to "Manifold Options" on page 27.
- \*3 The plug for individual supply is mounted on the first station to block the air supply passage to the D side. Option M can be selected after second station.
- \*4 Manual override to release vacuum (V) port to atmosphere. When option R is selected, option Y cannot be used together.
- \*5 When "Y" is selected, the energy saving function is not available. When the vacuum generation is stopped, the vacuum (V) port is released to the atmosphere.
- \* When option Y is selected, "V" for 4 exhaust sealing valve cannot be selected.

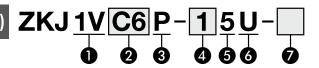


## How to Order (Single unit for manifold)





Positive pressure unit (5-port valve)



#### Unit specifications

Symbol	Туре
1V	Positive pressure unit

\* When using a positive pressure unit with the initial SI unit settings, diagnostic information for pressure sensor disconnection will be issued. Therefore, be sure to change the SI unit settings in accordance with the selected individual unit.

#### 2 Output A(4), B(2) port, supply P(1) port

Symbol	Standard Output (A, B) port		Supply (P) port
C6	Metric	ø6	
C8	ivietric	ø8	Dlug
N7	Inoh	ø1/4"	Plug
N9	Inch	ø5/16"	
C6U	Marketa	ø6	ø6*1
C8U	Metric	ø8	ø8*1
N7U	Inch	ø1/4"	ø1/4"* <sup>1</sup>
N9U	IIICH	ø5/16"	ø5/16"* <sup>1</sup>

<sup>\*1</sup> Select this option when selecting the plug for individual supply option or when increasing the flow rate from the supply port.

#### 3 Exhaust E(3/5) port

Symbol	Exhaust type
Р	Port exhaust*1

\*1 Port size of exhaust port; mm: ø8. inch: ø5/16"

### 4 Type of actuation

Symbol	Specifications			
1	2-position	Single		
2	2-position	Double		
A	4-position dual 3-port	N.C./N.C.		

### 6 Rated voltage

Symbol	Voltage
5	24 VDC

#### 6 Light/surge voltage suppressor and common specification

Symbol	With light	Surge voltage suppressor	Common specification
U	Yes	Yes	Non-polar

### Option

13

Symbol	Specifications			
Nil	Without option			
М	Plug for individual supply*1, *2 (Blocking the air supply passage to the D side)			

\*1 The supply (P) port for vacuum manifold is mounted only on the U side.

When a vacuum unit/positive pressure unit with a built-in plug for individual supply is selected, be sure to select a supply (P) port via 2 for the unit immediately to the D side of the aforementioned unit.

\*2 Station 1 cannot be selected as it has a built-in plug for individual supply to prevent air from passing to the D side.

# Vacuum Manifold for Fieldbus System **ZKJ** Series





\* The solenoid valve mounted on this product is equivalent to the SMC JSY3000 series 5-port solenoid valve.

For details on solenoid valve functions, refer to the Operation Manual of the JSY3000 series on the SMC website (https://www.smcworld.com).

5-port solenoid valve JSY3000 series

ZKJ-JSY3 00-5U

Vacuum manifold for fieldbus system ZKJ series

ZKJ \_\_\_\_\_\_ 5U - T1

Combination of supply valve and release valve

#### **Specifications**

#### Vacuum Unit\*1

accum one							
Model			ZKJ07	ZKJ10	ZKJ12	ZKJ15	
Fluid				Д	ir		
Nozzle size [mm]			0.7	1.0	1.2	1.5	
Standard supply pressure [MPa]				0	.4		
Max. vacuum pre	Max. vacuum pressure [kPa]*2			-8	39		
	Port	Without exhaust sealing valve	31	53	63	74	
Max. suction flow rate	exhaust	With exhaust sealing valve	30	48	57	_	
[L/min (ANR)]*2, *3	High-noise reduction	Without exhaust sealing valve	31	51	60	68	
silencer exhaust		With exhaust sealing valve	30	45	54	_	
Air consumption	[L/min (ANF	R)]*2	26	48	68	102	
Supply pressure			0.3 to 0.5				
Type of actuation	1		Supply valve: N.C., Release valve: N.C. (ZKJ-JSY3A) Supply valve: N.O., Release valve: N.C. (ZKJ-JSY3E)				
Response time (a	at 0.5 MPa)*	4		23 ms	or less		
Max. operating f	requency			3	Hz		
Manual override			Non-locking push type				
Power consump	tion		0.4 W				
	Operating temperature range		0 to 50°C (No condensation)				
	_ Vibration resistanc		30 m/s <sup>2</sup>				
Environmental resistance	Impact resi	stance*6	150 m/s <sup>2</sup>				
resistance	Withstand	Withstand voltage		500 VAC for 1 minute between terminals and FE			
	Insulation r	esistance	500 VDC, 10 M $\Omega$ or more between terminals and FE				
	Enclosure*7			IP65			
Standards			CE/UKCA m	narking (EMC	directive/Rol	HS directive)	

- \*1 The supply valve and release valve mounted on this product is the SMC dual 3-port valve JSY3000 series. Refer to the **Web Catalog** for details on the JSY3000 series.
- \*2 Values are at the standard supply pressure and based on SMC's measurement standards. They depend on atmospheric pressure (weather, altitude, etc.) and the measurement method.
- \*3 If the vacuum port diameter is ø6 or ø1/4", Max. Suction flow rate is reduced by 15% or less.
- \*4 It shows supply valve/release valve specification. Based on dynamic performance test, JIS B 8419:2010. (Coil temperature: 20°C, at rated voltage)
- \*5 The characteristics are satisfied when tested for 2 hours in each of the X, Y and Z directions at 10 to 500 Hz without energization. (Initial value)
- \*6 The characteristics are satisfied when tested one time in each of the X, Y and Z directions without energization. (Initial value)
- \*7 Cannot be used in an environment where oil such as cutting oil splashes or it is constantly exposed to water

Take appropriate protective measures.



# **ZKJ** Series



### **Specifications**

#### **Positive Pressure Unit**

	Model	ZKJ1V□P-15U	ZKJ1V□P-25U	ZKJ1V□P-A5U	
Fluid		Air			
Supply pressure range [MPa]			0.3 to 0.5		
Type of actuation		2-position single	2-position double	4-position dual 3-port valve (N.C./N.C.)	
Response tir	me*1	18 ms or less	12 ms or less	23 ms or less	
Max. operati	ng frequency	5 Hz			
Manual override		Non-locking push type			
Power consu	umption	0.4 W			
	Operating temperature range	0 to 50°C (No condensation)			
	Vibration resistance*2	30 m/s <sup>2</sup>			
Environmental	Impact resistance*3	150 m/s <sup>2</sup>			
resistance	Withstand voltage	500 VAC for 1 minute between terminals and FE			
	Insulation resistance	500 VDC, 10 M $\Omega$ or more between terminals and			
	Enclosure*4	IP65			
Standards		CE/UKCA marking (EMC directive/RoHS directive)			

- \*1 It shows solenoid valve specification. Based on dynamic performance test, JIS B 8419:2010. (Coil temperature: 20°C, at rated voltage)
- \*2 The characteristics are satisfied when tested for 2 hours in each of the X, Y and Z directions at 10 to 500 Hz without energization. (Initial value)

  \*3 The characteristics are satisfied when tested one time in each of the X, Y and Z directions
- without energization. (Initial value)
- \*4 Cannot be used in an environment where oil such as cutting oil splashes or it is constantly exposed to water

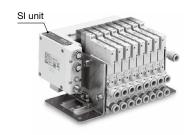
Take appropriate protective measures.

#### **Positive Pressure Unit: Flow Rate Characteristics**

	Port size		1 → 4/2 (P −	→ A/B)	$4/2 \rightarrow 3/5 \text{ (A/B} \rightarrow \text{E)}$								
Model	1, 3/5 (P, E)	4, 2 (A, B)	C [dm <sup>3</sup> /(s·bar)]	b	C [dm <sup>3</sup> /(s·bar)]	b							
ZKJ1VC6P-15U			1.33	0.38	1.44	0.39							
ZKJ1VC6P-25U		C6	C6	C6	C6	C6	C6	C6	C6 1.55	1.33	0.50	1.44	0.39
ZKJ1VC6P-A5U	C8		1.07	0.34	1.40	0.46							
ZKJ1VC8P-15U			1.46	0.46	1.44	0.28							
ZKJ1VC8P-25U		C8	1.40	0.46	1.44	0.20							
ZKJ1VC8P-A5U			1.15	0.41	1.40	0.32							

st Calculation of effective area "S" and sonic conductance "C": S = 5.0 x C Values measured in accordance with ISO 6358:1989, JIS B 8390:2000





### **Specifications**

# Max. Number of Manifold Stations that Can Operate Simultaneously $^{\!\!\!\!\!\!\!\!^{1}}$

Model	ZKJ07	ZKJ10	ZKJ12	ZKJ15
Air supply port: 1 port  · U-side end plate P port (ø8)	16	6	5	3
Air supply port: 2 ports  · U-side end plate P port (ø8), Equipped with 1 vacuum unit with a P port (ø6)	16	8	7	4

<sup>\*1</sup> Values are the number of stations that can be generated vacuum simultaneously.

#### Noise Level (Reference values)

Model	ZKJ07	ZKJ10	ZKJ12	ZKJ15
Noise level [dB(A)]	52	63	67	71

<sup>\*</sup> Values are at the standard supply pressure.

#### Weight

Manifold stations (All vacuum units)	4 stations	8 stations	12 stations	16 stations
Weight [kg]	1.7	2.5	3.3	4.1

<sup>\*</sup> When the blanking plate is mounted, please subtract 0.1 [kg] per unit.

### SI Unit (PROFINET) (For details, refer to the Operation Manual.)

	Model		EX260-VPN1		
	Power supply for control/	Power supply voltage	24 VDC ±10%		
Electrical	input	Internal current consumption	100 mA or less		
	Power supply for output	Power supply voltage	24 VDC +10%, -5%		
	Protocol		PROFINET		
	Device type		PROFINET IO		
	Configuration file*1		GSD File		
	Version		PROFINET Specification Version 2.3		
	Communication	n speed	100 Mbps full duplex		
Communication	Applicable fun	ction	MRP function MRPD function Fast Start Up function Shared Device function Conformance Class C Net Load Class III		
Vacuum Applicable function		ction	Energy saving Valve protection Zero-clear function		

<sup>\*1</sup> The configuration file can be downloaded from the SMC website: https://www.smcworld.com

### SI Unit (EtherNet/IP $^{\text{TM}}$ ) (For details, refer to the Operation Manual.)

	Model		EX260-VEN1	
	Power supply for control/	Power supply voltage	24 VDC ±10%	
Electrical	input	Internal current consumption	100 mA or less	
	Power supply for output	Power supply voltage	24 VDC +10%, -5%	
	Protocol		EtherNet/IP <sup>TM</sup>	
	Device type		2Bh (Generic Device)	
	Configuration	file*1	EDS File	
Communication	Conformance t	est revision	CT18	
Communication	Communication	n speed	10 M/100 Mbps	
	Applicable fun	ction	DLR function QuickConnect <sup>TM</sup> function Web server function	
Vacuum	Applicable fun	ction	Energy saving Valve protection Zero-clear function	

<sup>\*1</sup> The configuration file can be downloaded from the SMC website: https://www.smcworld.com



Values are with 1 vacuum unit generating vacuum pressure adequately for adsorption with high-noise reduction silencer. (Not guaranteed values)

### **Specifications**

#### SI Unit (IO-Link) (For details, refer to the Operation Manual.)

	Model		EX260-VIL1	
	Power supply for control/	Power supply voltage	24 VDC ±10%	
Electrical	input	Internal current consumption	100 mA or less	
	Power supply for output	Power supply voltage	24 VDC +10%, -5%	
	Protocol		IO-Link	
	IO-Link type		Device	
	Port class		Class B	
Communication	Configuration	file*1	IODD File	
Communication	Version		V1.1	
	Communication	n speed	COM2 (38.4 kbps)	
	Applicable fun	ction	ISDU Data Storage	
Vacuum	/acuum Applicable function		Energy saving Valve protection Zero-clear function	

<sup>\*1</sup> The configuration file can be downloaded from the SMC website: https://www.smcworld.com

#### SI Unit (EtherCAT) (For details, refer to the Operation Manual.)

	Model		EX260-VEC1	
	Power supply for control/	Power supply voltage	24 VDC ±10%	
Electrical	input	Internal current consumption	100 mA or less	
	Power supply for output Voltage		24 VDC +10%, -5%	
	Protocol		EtherCAT	
	Configuration	file*1	ESI File	
Communication	Version		Conformance Test Record V2.3.0	
Communication	Communication	n speed	100 Mbps	
	Applicable fun	ction	CoE FoE	
Vacuum Applicable function			Energy saving Valve protection Zero-clear function	

 $<sup>*1 \ \</sup> The \ configuration \ file \ can \ be \ downloaded \ from \ the \ SMC \ website: https://www.smcworld.com$ 

#### **Control Unit Specifications**

	Model	ZKJ-S004-A	ZKJ-S008-A	ZKJ-S012-A	ZKJ-S016-A
Station		4	8	12	16
	Pressure sensor	4	8	12	16
Input	Pressure sensor short circuit detection/Protection circuit	Built-in (Common detection/protection)			
	Number of valve outputs	8	16	24	32
Output	Valve short circuit detection/ Protection circuit	Built-in	(Individual d	letection/pro	tection)

#### **Pressure Sensor Specifications**

(For details, refer to the PSE54 $\square$  series in the **Web Catalog**, and the Operation Manual.)

Item		Specifications	
Rated pressure	Without exhaust sealing valve	-100 to 100 [kPa]	
range	With exhaust sealing valve	-100 to 200 [kPa]	
Withstand pressure*1		500 [kPa]	
Accuracy		±3% F.S.	
Current consumption		15 mA or less	
Sensor pressure	receiving area	Silicon	

<sup>\*1</sup> Do not use the product to drive an actuator such as a cylinder (when release pressure is constantly applied).

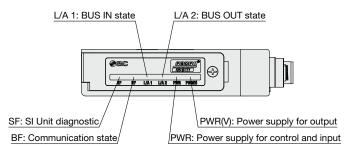


#### Connector/LED Indicator

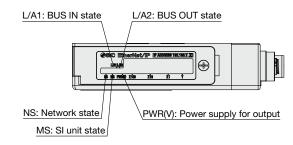


Part no.	EX260-VPN1	EX260-VEN1
Protocol	PROFINET	EtherNet/IP <sup>TM</sup>
Communication connector (M12) BUS OUT	4-pin, Socket, D-coded	4-pin, Socket, D-coded
Communication connector (M12) BUS IN	4-pin, Socket, D-coded	4-pin, Socket, D-coded
Ground terminal	M3	M3
Power supply connector (M12)	4-pin, Plug, A-coded	4-pin, Plug, A-coded

#### **EX260-VPN1**



#### **EX260-VEN1**

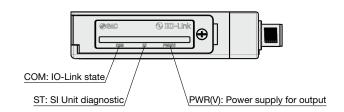


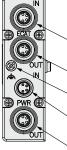


Part no.	EX260-VIL1
Protocol	IO-Link
Communication/Power connector (M12)*1	5-pin, Plug, A-coded
Ground terminal	M3

<sup>1</sup> The communication line, Power supply for control and input line, and the power supply for output line are connected using the same cable.

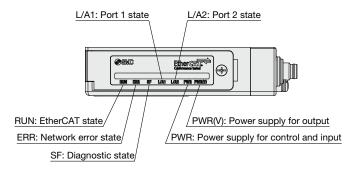
#### **EX260-VIL1**





Part no.	EX260-VEC1
Protocol	EtherCAT
Communication connector (M8) ECAT IN	4-pin, Socket, A-coded
Communication connector (M8) ECAT OUT	4-pin, Socket, A-coded
Ground terminal	M3
Power supply connector (M8) PWR IN	4-pin, Plug, A-coded
Power supply connector (M8) PWR OUT	4-pin, Socket, A-coded

#### **EX260-VEC1**



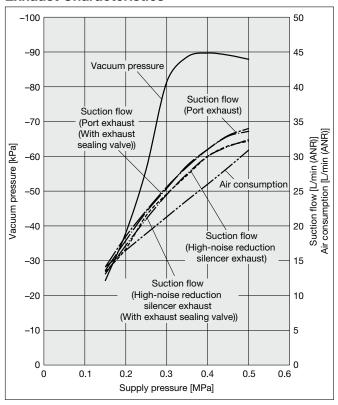


- Values are based on standard of SMC measurements. They depend on atmospheric pressure (weather, altitude, etc.) and measurement method.
- \* The flow rate characteristics correspond to the standard supply pressure.

#### Exhaust Characteristics/Flow Rate Characteristics (Representative value)

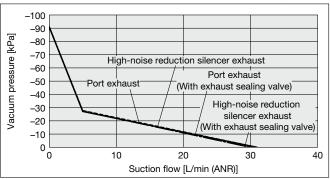
#### ZKJ07

#### **Exhaust Characteristics**



#### **Flow Rate Characteristics**

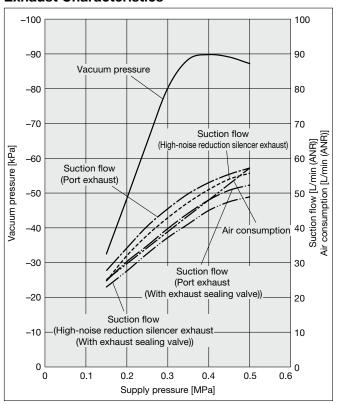
Supply pressure: 0.4 MPa (Standard supply pressure)



\* Port exhaust: V port ø8, no exhaust port piping

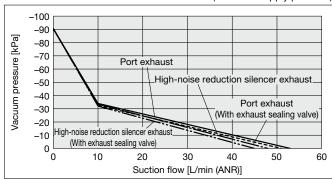
#### ZKJ<sub>10</sub>

#### **Exhaust Characteristics**



# Flow Rate Characteristics

Supply pressure: 0.4 MPa (Standard supply pressure)



\* Port exhaust: V port ø8, no exhaust port piping

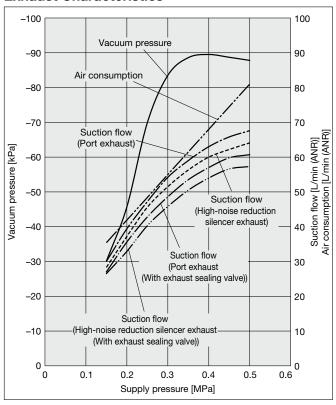
# Vacuum Manifold for Fieldbus System **ZKJ** Series

- \* Values are based on standard of SMC measurements. They depend on atmospheric pressure (weather, altitude, etc.) and measurement method.
- \* The flow rate characteristics correspond to the standard supply pressure.

#### Exhaust Characteristics/Flow Rate Characteristics (Representative value)

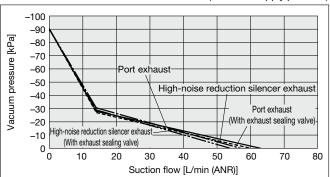
#### ZKJ12

#### **Exhaust Characteristics**



#### **Flow Rate Characteristics**

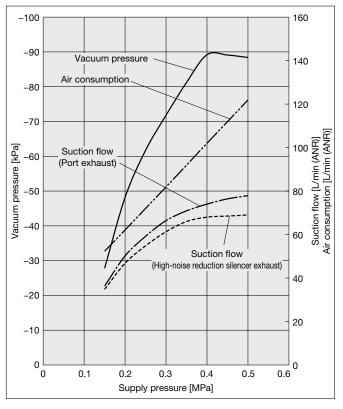
Supply pressure: 0.4 MPa (Standard supply pressure)



\* Port exhaust: V port ø8, no exhaust port piping

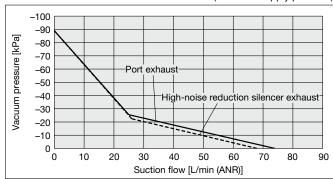
#### ZKJ15

#### **Exhaust Characteristics**



#### Flow Rate Characteristics

Supply pressure: 0.4 MPa (Standard supply pressure)



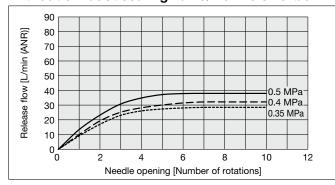
\* Port exhaust: V port ø8, no exhaust port piping



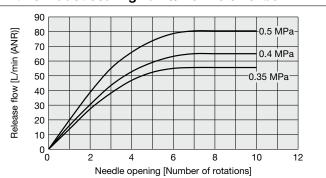
### Vacuum Release Flow Rate Characteristics (Representative value)

The graph shows the flow rate characteristics at different supply pressures when the vacuum release flow adjusting needle is open from the fully closed state. The actual suction flow at the point of suction varies depending on the piping conditions.

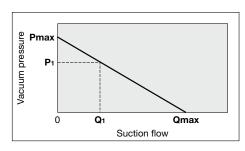
#### Without exhaust sealing valve/Nozzle size: Ø0.7



#### With exhaust sealing valve/Nozzle size: Ø0.7



#### How to Read the Flow Rate Characteristics Graph



The flow rate characteristics indicate the relationship between the vacuum pressure and the suction flow of the ejector. They also show that when the suction flow changes, the vacuum pressure also changes. In general, this indicates the relationship at the ejector's standard operating pressure. In the graph, **Pmax** indicates the max. vacuum pressure, and **Qmax** indicates the max. suction flow. These are the values that are published as specifications in catalogs, etc. Changes in vacuum pressure are explained in the order below.

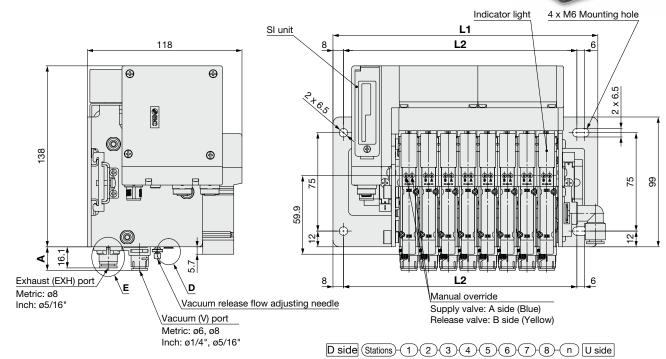
- If the ejector's suction port is closed and sealed tight, the suction flow becomes "0," and the vacuum pressure increases to the max. (Pmax).
- 2. If the suction port is opened gradually and air is allowed to flow (the air leaks), the suction flow increases, and the vacuum pressure decreases. (The condition of P<sub>1</sub> and Q<sub>1</sub>)
- If the suction port is opened completely, the suction flow increases to the max. (Qmax), while the vacuum pressure then drops almost to "0" (atmospheric pressure).

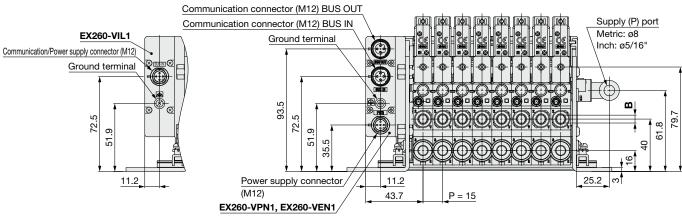
As described above, the vacuum pressure changes when the suction flow changes. In other words, when there is no leakage from the vacuum (V) port, the vacuum pressure can reach its maximum, but as the amount of leakage increases, the vacuum pressure decreases. When the amount of leakage and the maximum suction flow become equal, the vacuum pressure becomes almost zero. When adsorbing workpieces which are permeable, subject to leakage, etc., caution is required as the vacuum pressure will not be very high.

# Vacuum Manifold for Fieldbus System **ZKJ** Series

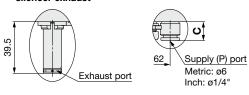
#### **Dimensions**

#### Vacuum unit: ZZKJ□-□-□





# For high-noise reduction With supply (P) port silencer exhaust



				EX	260-\	/EC1			
						\	IN	1	Communication connector (M8) ECAT IN
	7								Communication connector (M8) ECAT OUT
1		ī	1	<u> </u>			D OUT		Ground terminal
	91.9	74.9	66.4	54.7	37.7		D PWR &		Power supply connector (M8) PWR IN  Power supply connector (M8) PWR OUT
n	, ]	, ,	, ,	, ,	, ,	-	11	1.2	

							[mm]
	Manifold stations			3	12		16
L1		142	20	02	262	;	322
L2		118	11	78	238	:	298
Port type		,	Α	Heyann	n width across fla	ats <b>R</b>	С
1 Ort type		,		Tionago	ii widiii dolooo iii	ם טוג	_
Metric	C6	ø6	14.8		4		9.7
Menic	C8	ø8	18		6		_

16.3

18

4.76

12.3

ø1/4"

ø5/16"

N7

N9

Inch

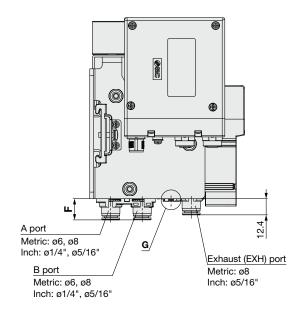


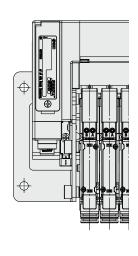
# **ZKJ** Series

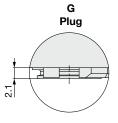
### **Dimensions**

Positive pressure unit: ZZKJ□-□-□



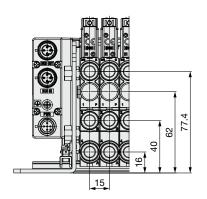










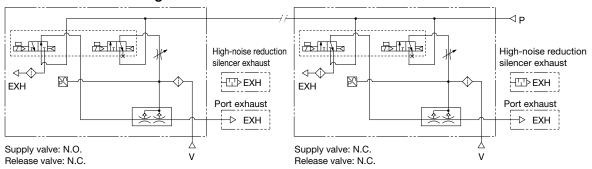


				[mm]
P	ort typ	е	F	Н
Metric	C6	ø6	14.5	10.7
	C8	ø8	16.2	12.4
Inch	N7	ø1/4"	14.5	10.7
IIICII	N9	ø5/16"	16.2	12.4

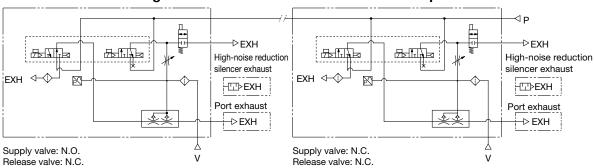
### **Air Circuit Diagram**

#### Vacuum unit

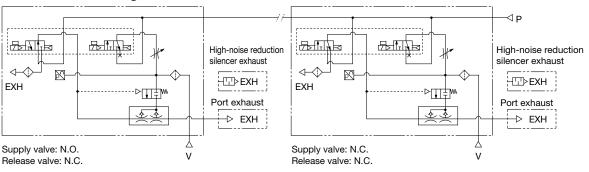
#### Without exhaust sealing valve

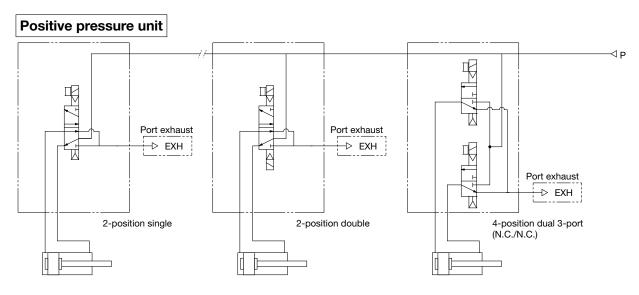


#### Without exhaust sealing valve/With manual override for residual pressure release



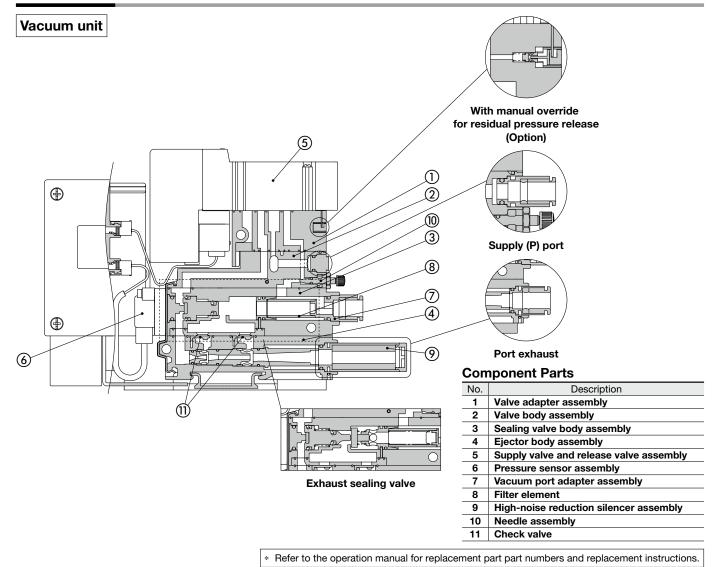
#### With exhaust sealing valve

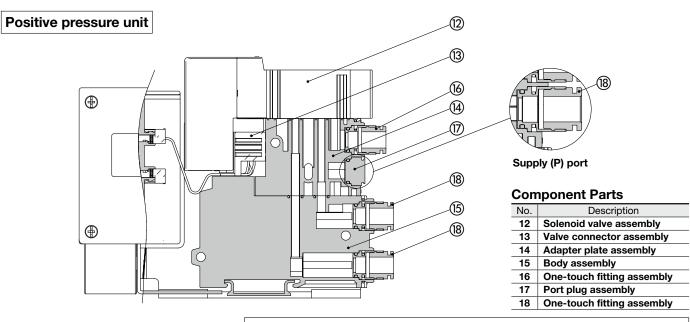




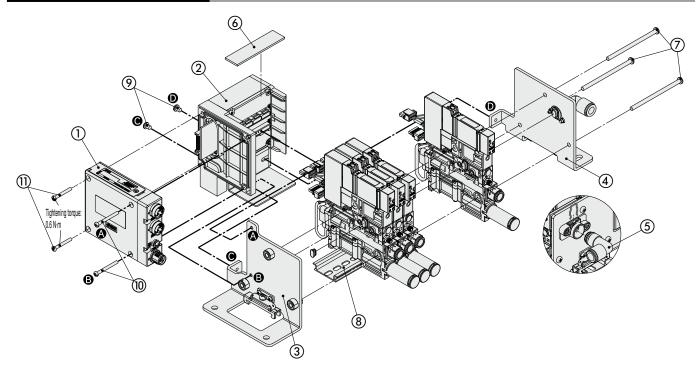
# **ZKJ** Series

#### Construction





# **Exploded View of Manifold**



#### **Component Parts**

	_ =
No.	Description
1	SI unit
2	Control unit
3	D-side end plate assembly
4	U-side end plate assembly
5	Elbow type One-touch
5	Elbow type One-touch fitting assembly

No.	Description	
6	Protection plate	
7	Tension bolt	
8	DIN rail	
9	Round head combination screw	
10	Round head combination screw	
11	Round head combination screw	

<sup>\*</sup> Refer to the operation manual for replacement part part numbers and replacement instructions.

# ZKJ Series Manifold Options

#### **Manifold Options**

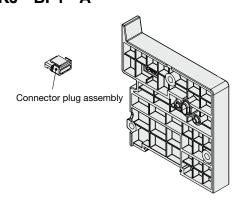
#### ■ Blanking plate

[With two connector plug assembly]

For use on unused manifold stations where a vacuum unit/positive pressure unit is not mounted

\* When using a blanking plate with the initial SI unit settings, diagnostic information for pressure sensor disconnection will be issued. Therefore, be sure to change the SI unit settings in accordance with the selected individual unit.

#### ZKJ - BP1 - A



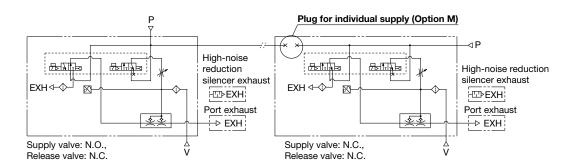
#### ■ Plug for individual supply

By placing "Plug for individual supply" in an ejector manifold's pressure supply passage, two different pressures can be supplied to one manifold.

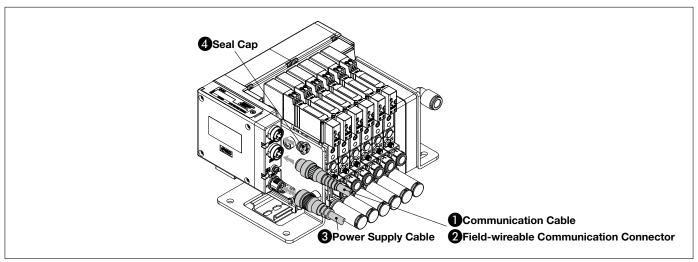
The supply (P) port for vacuum manifold is mounted only on the U side. When a vacuum unit/positive pressure unit with a built-in plug for individual supply is selected, be sure to select a supply (P) port for the model number of the unit immediately to the D side of the aforementioned unit.

#### **ZK2-MP2F-A**





# **ZKJ** Series **Accessories**



<sup>\*</sup> SMC does not provide communication cables or power cables (M8 connector) for the EtherCAT compatible type. Order a cable from another cable manufacturer.

### Communication Cable

050

### For PROFINET For EtherNet/IP™

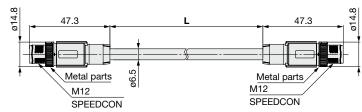
#### EX9-AC 005 EN-PSPS (With connector on both sides (Plug/Plug))

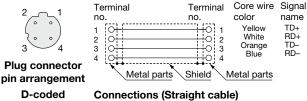
#### Cable length (L) 005 500 mm 010 1000 mm 020 2000 mm 030 3000 mm

5000 mm

Min. bending radius (Fixed)

100	10000 mm	
Item		Specifications
Cable O.D.		ø6.5 mm
Conductor nominal cross section		0.34 mm <sup>2</sup> /AWG22
Wire O.D. (Including insulator)		1.55 mm





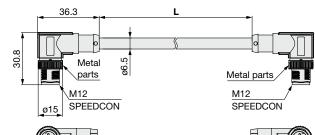
Plug connector pin arrangement **D-coded** 

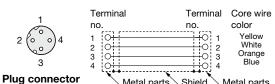
#### EX9-AC 005 EN-PAPA (With angled connector on both sides (Plug/Plug))

19.5 mm

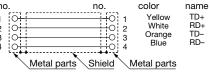
#### Cable length (L) 005 500 mm 010 1000 mm 020 2000 mm 030 3000 mm 050 5000 mm 100 10000 mm

Item	Specifications
Cable O.D.	ø6.5 mm
Conductor nominal cross section	0.34 mm <sup>2</sup> /AWG22
Wire O.D. (Including insulator)	1.55 mm
Min. bending radius (Fixed)	19.5 mm





Connections (Straight cable)



Signal

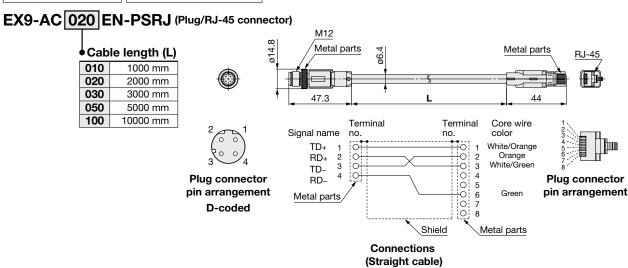
Plug connector pin arrangement **D-coded** 



# **ZKJ** Series

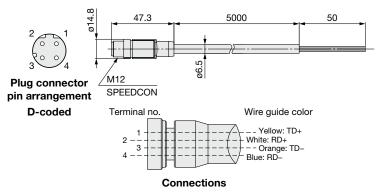
### **①** Communication Cable

# For PROFINET For EtherNet/IP™



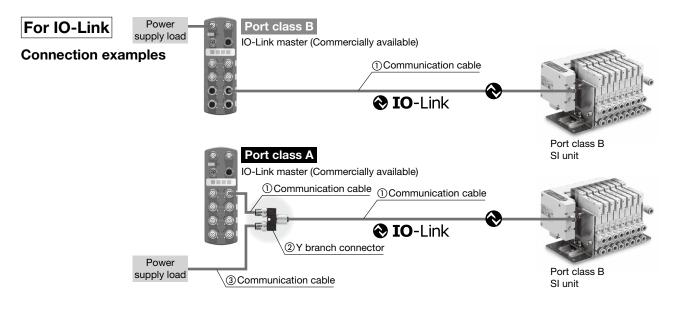
Item	Specifications
Cable O.D.	ø6.4 mm
Conductor nominal cross section	0.14 mm <sup>2</sup> /AWG26
Wire O.D. (Including insulator)	0.98 mm
Min. bending radius (Fixed)	26 mm

#### PCA-1446566 (Plug)

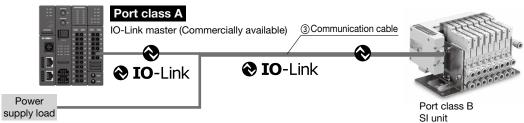


Item	Specifications
Cable O.D.	ø6.5 mm
Conductor nominal cross section	0.34 mm <sup>2</sup> /AWG22
Wire O.D. (Including insulator)	1.55 mm
Min. bending radius (Fixed)	19.5 mm

#### Communication Cable

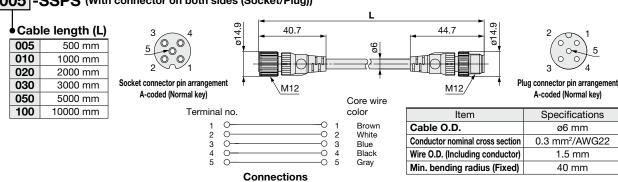


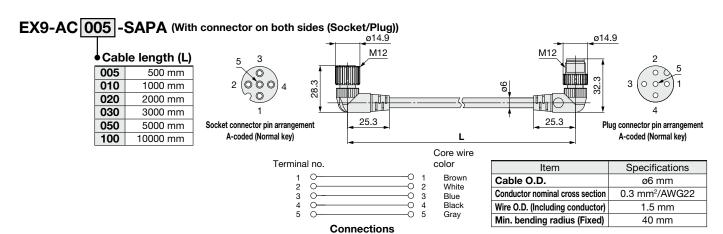
#### Terminal block wiring type



#### ① Communication cable







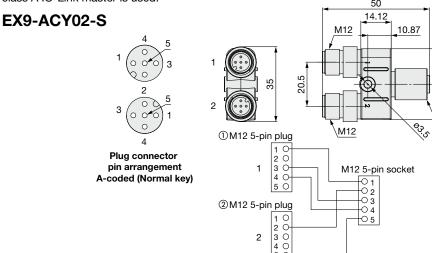
#### Communication Cable

#### For IO-Link

#### ②Y branch connector

This connector is used to supply output power by branching the IO-Link communication cable when a port class A IO-Link master is used.

5 0







Socket connector pin arrangement A-coded (Normal key)

#### Power cable side pin arrangement for output when using Y branch connector

		<u> </u>
1	_	Unused
2	SV24V	+24 V for output
3	_	Unused
4	_	Unused
5	SV0V	0 V for output

#### ③ Communication cable

# EX500-AP 050

#### Cable length (L)

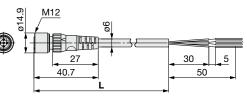
**010** 1000 mm

<b>♦</b> Connector specification		
S	Straight	
Α	Angled	

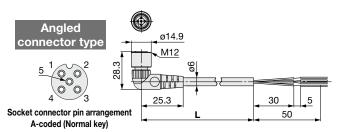




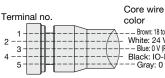
Socket connector pin arrangement A-coded (Normal key)



Item	Specifications
Cable O.D.	ø6 mm
Conductor nominal cross section	0.3 mm <sup>2</sup> /AWG22
Wire O.D. (Including insulator)	1.5 mm
Min. bending radius (Fixed)	40 mm



Item	Specifications
Cable O.D.	ø6 mm
Conductor nominal cross section	0.3 mm <sup>2</sup> /AWG22
Wire O.D. (Including insulator)	1.5 mm
Min. bending radius (Fixed)	40 mm



M12

— Brown: 18 to 30 VDC (Power supply for control and input)\* 1, Not connected\*2
White: 24 VDC +10%/-5% (Power supply for output)
— Blue: 0 V (Power supply for control and input)\* 1, Not connected\*2
Black: 10-Link communication\* 1, Not connected\*2
— Gray: 0 V (Power supply for output)

Connections (IO-Link)

- \*1 When used as an IO-Link communication cable
- \*2 When used as a solenoid valve power supply cable

#### **1** Communication Cable



With connector on one side (Socket)
Cable length: 10000 mm

EX500-AP100-S-X1

• Connector specification

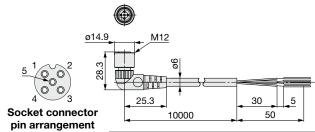
S	Straight
Α	Angled

### 

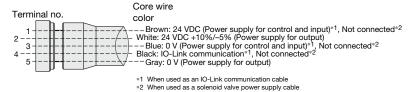
pecifications
ø6 mm
mm²/AWG22
1.5 mm
40 mm

#### Angled connector type

A-coded

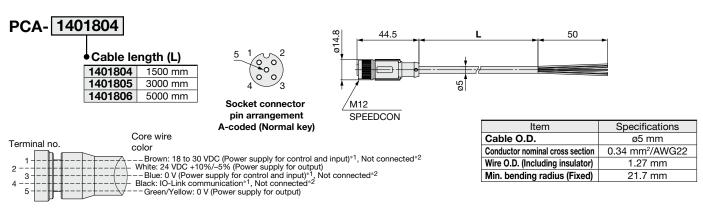


Item	Specifications
Cable O.D.	ø6 mm
Conductor nominal cross section	0.3 mm <sup>2</sup> /AWG22
Wire O.D. (Including insulator)	1.5 mm
Min. bending radius (Fixed)	40 mm



- \*2 When used as a solehold valve
- Commontions (IQ Limb)

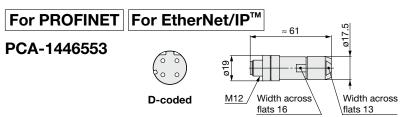
#### Connections (IO-Link)



Connections (IO-Link)

\*1 When used as an IO-Link communication cable \*2 When used as an output power supply cable

#### 2 Field-wireable Communication Connector

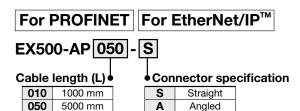


#### **Applicable Cable**

Item	Specifications
Cable O.D.	4.0 to 8.0 mm
Wire gauge (Stranded wire cross section)	0.14 to 0.34 mm <sup>2</sup> /AWG26 to 22

The table above shows the specifications for the applicable cable. Adaptation for the connector may vary on account of the conductor construction of the electric wire.

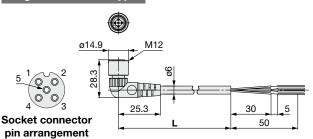
## **3** Power Supply Cable



#### 

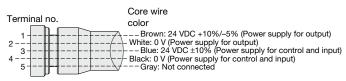
Item	Specifications
Cable O.D.	ø6 mm
Conductor nominal cross section	0.3 mm <sup>2</sup> /AWG22
Wire O.D. (Including insulator)	1.5 mm
Min. bending radius (Fixed)	40 mm

#### Angled connector type



A-coded

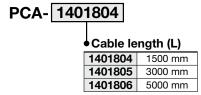
Item	Specifications
Cable O.D.	ø6 mm
Conductor nominal cross section	0.3 mm <sup>2</sup> /AWG22
Wire O.D. (Including insulator)	1.5 mm
Min. bending radius (Fixed)	40 mm





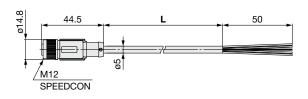
#### Connections (PROFINET)

#### Connections (EtherNet/IPTM)

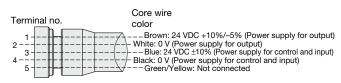


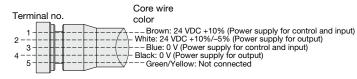


Socket connector pin arrangement A-coded



Item	Specifications
Cable O.D.	ø5 mm
Conductor nominal cross section	0.34 mm <sup>2</sup> /AWG22
Wire O.D. (Including insulator)	1.27 mm
Min. bending radius (Fixed)	21.7 mm





SMC

### Power Supply Cable



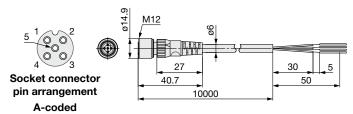
With connector on one side (Socket) Cable length: 10000 mm

EX500-AP100-|S|-X1

Connector specification

S	Straight
Α	Angled

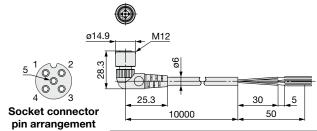
#### Straight connector type



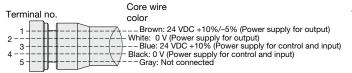
Item	Specifications
Cable O.D.	ø6 mm
Conductor nominal cross section	0.3 mm <sup>2</sup> /AWG22
Wire O.D. (Including insulator)	1.5 mm
Min. bending radius (Fixed)	40 mm

#### Angled connector type

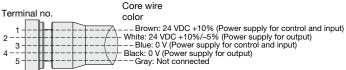
A-coded



Item	Specifications
Cable O.D.	ø6 mm
Conductor nominal cross section	0.3 mm <sup>2</sup> /AWG22
Wire O.D. (Including insulator)	1.5 mm
Min. bending radius (Fixed)	40 mm



**Connections (PROFINET)** 



#### Connections (EtherNet/IPTM)

## 4 Seal Cap (10 pcs.)

Use this on ports that are not being used for communication connector (M12, M8 connector socket).

Use of this seal cap maintains the integrity of the IP65 enclosure.

\* Tighten the seal cap with the prescribed tightening torque. (For M12: 0.1 N·m, For M8: 0.05 N·m)

# EX9-AW TS

#### Connector specification

TS For M12 connector socket (10 pcs.) For M8 connector socket (10 pcs.)

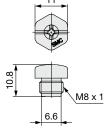
The EX260-VPN1 and EX260-VEN1 come with 1 seal cap, and the EX260-VEC1 comes with 2 seal caps.

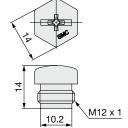
# **EX9-AWES**

#### **EX9-AWTS** For M8 connector socket For M12 connector socket









M8 connector (For socket)

For M12 connector socket



# **⚠** Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "Caution," "Warning" or "Danger." They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)\*1), and other safety regulations.

⚠ Danger: Danger indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

⚠ Warning: Warning indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.

Caution: Caution indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.

\*1) ISO 4414: Pneumatic fluid power - General rules and safety requirements for systems and their components ISO 4413: Hydraulic fluid power - General rules and safety requirements for systems and their components IEC 60204-1: Safety of machinery - Electrical equipment of machines - Part 1: General requirements ISO 10218-1: Robots and robotic devices - Safety requirements for industrial robots - Part 1:Robots

### **.** Warning

1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

2. Only personnel with appropriate training should operate machinery and equipment.

The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained

- 3. Do not service or attempt to remove product and machinery/ equipment until safety is confirmed.
  - 1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
  - 2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
  - 3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.
- 4. SMC products cannot be used beyond their specifications. They are not developed, designed, and manufactured to be used under the following conditions or environments. Use under such conditions or environments is not allowed.
  - 1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
  - 2. Use for nuclear power, railways, aviation, space equipment, ships, vehicles, military application, equipment affecting human life, body, and property, combustion equipment, entertainment equipment, emergency shut-off circuits, press clutches, brake circuits, safety equipment, etc., and use for applications that do not conform to standard specifications such as catalogs and operation manuals.
  - 3. Use for interlock circuits, except for use with double interlock such as installing a mechanical protection function in case of failure. Please periodically inspect the product to confirm that the product is operating properly.

#### **⚠** Caution

SMC develops, designs, and manufactures products to be used for automatic control equipment, and provides them for peaceful use in manufacturing industries.

Use in non-manufacturing industries is not allowed.

Products SMC manufactures and sells cannot be used for the purpose of transactions or certification specified in the Measurement Act of each country. The new Measurement Act prohibits use of any unit other than SI units in

#### Limited warranty and Disclaimer/ Compliance Requirements

The product used is subject to the following "Limited warranty and Disclaimer" and "Compliance Requirements".

Read and accept them before using the product.

#### **Limited warranty and Disclaimer**

- 1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered, whichever is first.\*2) Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
- 2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided. This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.
- 3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.
  - \*2) Suction cups (Vacuum pads) are excluded from this 1 year warranty. A suction cup (vacuum pad) is a consumable part, so it is warranted for a year after it is delivered.

Also, even within the warranty period, the wear of a product due to the use of the suction cup (vacuum pad) or failure due to the deterioration of rubber material are not allowed by the limited warranty.

#### Compliance Requirements

- 1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.
- 2. The exports of SMC products or technology from one country to another are governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of a SMC product to another country, assure that all local rules governing that export are known and followed.

- Edition B \* A positive pressure unit has been added.
  - \* The number of pages has been increased from 32 to 36

↑ Safety Instructions | Be sure to read the "Handling Precautions for SMC Products" (M-E03-3) and "Operation Manual" before use.

# SMC Corporation https://www.smcworld.com