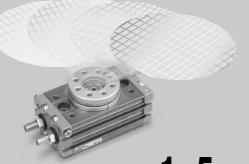
# **Low-Speed Rotary Actuator**

# CRQ2X/MSQX Series

CRQ2 Size: 10, 15, 20, 30, 40 MSQX Size: 10, 20, 30, 50

# Possible to transfer a workpiece at low-speed.

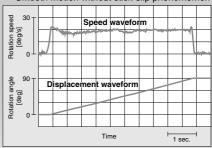


Rotation time adjustment range: 1 to 5 (s/90°)

ı	Model	Size	Rotati	on time	adjustm	ent rang	e (s/90°) 1 5
		10, 15, 20, 30, 40		1 to 5 (	0.7 to 5 f	r CRQ2>	(□10,15)
speed	MSQX	10, 20, 30, 50					
Standard	CRQ2	10, 15, 20, 30, 40	0.2 to	<b>1</b> (0.2 to	0.7 for C	RQ2□10	,15)
Starioard	MSQ	10, 20, 30, 50					

Realized a stable motion at 5 s/90°.

Smooth motion without stick-slip phenomemon



Measurement conditions / Fluid: Air

Mounting original extension of the CRQ2, MSQ series

Dimensions compatible with the CRQ2, MSQ series

CRO2X Series

MSQX Series

# CRQ2X/MSQX Series **Model Selection**

\* The selection procedure of the rotary for low-speed is the same as for an ordinary rotary. If the rotation time exceeds 2s per 90°, however, the necessary torque and the kinetic energy are calculated with rotation time of 2s per 90°.

### Selection Procedure

### Remarks

### Selection Example

### Operating conditions

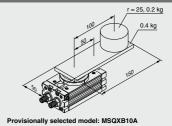
Operating conditions are as follows:

- · Provisionally selected model
- · Operating pressure: MPa
- Mounting position Load type
- Static load: N·m Resistance load: N·m Inertial load: N.m.
- · Load dimension: m
- · Load mass: kg
- Rotation time: s · Rotation angle: rad

. See P. 380 for load type.

 $90^{\circ} = \pi/2$ rad

. The unit of the rotation angle is Radians  $180^{\circ} = \pi rad$ 



Operating pressure: 0.3 MPa Mounting position: Vertical, Type of load: Inertial load Rotation time: t = 6s Rotation angle:  $\theta = \pi rad (180^{\circ})$ 

### Calculation of moment of inertia

Calculate the moment of inertia of the load.

⇒ P. 379

. If the moment of inertia of the load is made up of multiple components, calculate the moment of inertia of each component and add them

Load 1 moment of inertia: I1 Load 2 moment of inertia: I2  $I_2 = 0.2 \times \frac{0.025^2}{2} + 0.2 \times 0.1^2 = 0.002063$ Total moment of inertia: I

### Calculation of necessary torque

Calculate necessary torque corresponding to the load type, and ensure it is within effective torque range.

- . Static load (Ts)
- Necessary torque T = Ts
- · Resistance load (Tf) Necessary torque T = Tf x (3 to 5)
- · Inertial load (Ta)
- Necessary torque T = Ta x 10

- . When calculating the inertial load, if the rotation time exceeds 2s per 90°, inertial load is calculated with rotation time of 2s per 90°.
- . Even for resistance load, when the load is rotated, necessary torque calculated from inertial load shall be added

Necessary torque T = Tf x (3 to 5) + Ta

Inertial load: Ta Ta = I · 🖮  $\dot{\omega} = \frac{2\theta}{t^2} [\text{rad/s}^2]$ Necessary torque: T T = Ta x 10 = 0.003896 x  $\frac{2 \times \pi}{4^2}$  x 10 = 0.015 [N·m] (t is calculated with 2s per 90°.) 0.015 N·m < Effective torque OK

 $I = I_1 + I_2 = 0.003896 [kg \cdot m^2]$ 

### Checking rotation time

Confirm that it is within the adjustable range of rotation time.

→ P. 381

. Converted to the time per 90° for comparison. (For comparison 6s/180° is converted to 3s/90°.)

1.0 ≤ t ≤ 5 t = 3s/90° OK

### Calculation of kinetic energy

Confirm that the load's kinetic energy is within the allowable value.

Can be confirmed by the graph of the moment of inertia and the rotation time.

⇒ P. 381

- . If the rotation time exceeds 2s per 90°, kinetic energy is calculated with rotation time of 2s per 90°.
- . If the allowable value is exceeded, an external cushioning mechanism such as an absorber needs to be installed.

 $E = \frac{1}{2} \cdot I \cdot \omega^2$ 

 $\omega = \frac{2 \cdot \theta}{}$ Kinetic energy  $\frac{1}{2}$  x 0.003896 x  $\left(\frac{2 \times \pi}{4}\right)^2$  = 0.0048 [J] (t is calculated with 2s per 90°.) 0.0048 [J] < Allowable energy OK

### Checking allowable load

Check if the load applied to the product is within the allowable range. . If the allowable value is exceeded, an external bearing needs to be installed.

 $M = 0.4 \times 9.8 \times 0.05 + 0.2 \times 9.8 \times 0.1$ = 0.392 [N·m] 0.392 [N·m] < Allowable moment load OK

Calculation of air consumption and necessary air quantity

Calculate air consumption and necessary air quantity as required. ⇒ P. 383

# Model Selection CRQ2X/MSQX Series

### Equation Table of Moment of Inertia (Calculation of moment of inertia I) I: Moment of inertia (kg·m²) m: Load mass (kg)

### 1. Thin shaft

Position of rotational axis:

Perpendicular to the shaft through the center of gravity



$$I = m \cdot \frac{a^2}{4a^2}$$

### 2. Thin rectangular plate

Position of rotational axis:

Parallel to side b through the center of gravity



$$I = m \cdot \frac{a^2}{4a^2}$$

### 3. Thin rectangular plate (Including rectangular parallelepiped)

Position of rotational axis:

Perpendicular to the plate through the center of gravity



$$I = \mathbf{m} \cdot \frac{\mathbf{a}^2 + \mathbf{b}^2}{12}$$

### 4. Round plate (Including column)

Position of rotational axis:

Passing through the center axis



$$I = m \cdot \frac{r^2}{r}$$

### 5. Solid sphere

Position of rotational axis: Passing through the diameter



$$I = \mathbf{m} \cdot \frac{2 \, \mathbf{r}^2}{5}$$

### 6. Thin round plate

Position of rotational axis: Passing through the diameter



$$I = \mathbf{m} \cdot \frac{\mathbf{r}^2}{4}$$

### 7. Cylindrical

Position of rotational axis:

Passing through the diameter and the center of gravity



$$I = \mathbf{m} \cdot \frac{3 \, \mathbf{r}^2 + \mathbf{a}}{12}$$

### 8. When rotational axis and the center of the load are not concentric.

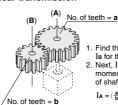


$$I = \mathbf{K} + \mathbf{m} \cdot \mathbf{L}^2$$

K: The moment of inertia around the center of gravity of the load

In case of 4. Round plate  $\mathbf{K} = \mathbf{m} \cdot \frac{\mathbf{r}^2}{2}$ 

### 9. Gear transmission



- 1. Find the moment of inertia
- Is for the rotation of shaft (B). 2. Next, Is is entered to find IA the moment of inertia for the rotation of shaft (A) as

$$I_A = (\frac{a}{b})^2 \cdot I_B$$

# CRQ2X/MSQX Series

## Load Type

Calculation method of necessary torque depends on the load type. Refer to the table below.

	Load type	
Static load: Ts	Resistance load: Tf	Inertial load: Ta
Only pressing force is necessary. (e.g. for clamping)	Weight or friction force is applied to rotating direction.	Rotate the load with inertia.
L F	Gravity is applied.	Center of rotation and center of gravity of the load are concentric.   Rotation shaft is vertical (up and down).
Ts = F·L  Ts: Static load (N·m) F: Clamping force (N) L: Distance from the rotation center to the clamping position (m)	Gravity is applied in rotating direction.  Tf = m·g·L  Friction force is applied in rotating direction.  Tf = μ·m·g·L  Tf : Resistance load (N·m)  m : Load mass (kg)  g : Gravitational acceleration 9.8 (m/s²)  L : Distance from the rotation center to the point of application of the weight or friction force (m)  μ : Friction coefficient	$\begin{aligned} & \text{Ta} = I \cdot \omega = I \cdot \frac{2\theta}{t^2} \\ & \text{Ta: Inertial load (N \cdot m)} \\ & I : \text{Moment of inertia } (kg \cdot m^2) \\ & \omega : \text{Angular acceleration } (rad/s^2) \\ & \theta : \text{Rotation angle } (rad) \\ & t : \text{Rotation time (s)} \end{aligned}$ For low speed rotary, if the rotation time exceeds 2s per $90^\circ$ , inertial load is calculated with rotation time of 2s per $90^\circ$ .
Necessary torque: <b>T</b> = <b>Ts</b>	Necessary torque: <b>T</b> = <b>Tf</b> x (3 to 5) <sup>Note)</sup>	Necessary torque: <b>T</b> = <b>Ta</b> x 10 <sup>Note)</sup>
Resistance load: Gravity or friction force is applie	ed to rotating direction.	Note) To adjust the speed, margin is necessary for

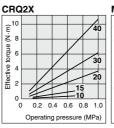
- Resistance load: Gravity or friction force is applied to rotating direction.
- Ex. 1) Rotation shaft is horizontal (lateral), and the rotation center and the center of gravity of the load are not concentric.
- Ex. 2) Load moves by sliding on the floor
- \* The total of resistance load and inertial load is the necessary torque. T = Tf x (3 to 5) + Ta x 10
- Not resistance load: Neither weight or friction force is applied in rotating direction.
  - Ex. 1) Rotation shaft is vertical (up and down).
  - Ex. 2) Rotation shaft is horizontal (lateral), and rotation center and the center of gravity of the load are not concentric.
  - \* Necessary torque is inertial load only.  $\mathbf{T} = \mathbf{Ta} \times 10$

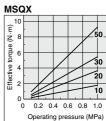
Note) To adjust the speed, margin is necessary for Tf and Ta.



### **Effective Torque**

											Un	it: N⋅m		
Model	C:	Operating pressure (MPa)												
Model 5	Size	0.1	0.15	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0		
	10	_	0.09	0.12	0.18	0.24	0.30	0.36	0.42	_	_	_		
	15	_	0.22	0.30	0.45	0.60	0.75	0.90	1.04	_	_	_		
CRQ2X	20	0.37	0.55	0.73	1.10	1.47	1.84	2.20	2.57	2.93	3.29	3.66		
	30	0.62	0.94	1.25	1.87	2.49	3.11	3.74	4.37	4.99	5.60	6.24		
	40	1.06	1.59	2.11	3.18	4.24	5.30	6.36	7.43	8.48	9.54	10.6		
	10	0.18	_	0.36	0.53	0.71	0.89	1.07	1.25	1.42	1.60	1.78		
мѕох	20	0.37	_	0.73	1.10	1.47	1.84	2.20	2.57	2.93	3.29	3.66		
WISQX	30	0.55	_	1.09	1.64	2.18	2.73	3.19	3.82	4.37	4.91	5.45		
	50	0.93	_	1.85	2.78	3.71	4.64	5.57	6.50	7.43	8.35	9.28		





Note 1) Values of operating torque in the above table are representative values, and not

guaranteed. Make use of the values as a reference when ordering.

Note 2) Except for cases when an external stopper is used, the holding torque at the operation end is half of the table value.

### Kinetic Energy/Rotating Time

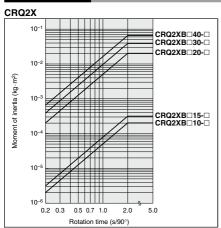
In a rotational movement, the kinetic energy of a load may damage the internal parts, even if the required torque for a load is small. Consider the moment of inertia and rotation time before selecting a model. (For model selection, refer to the moment of inertia and rotation time graph as shown on the below table.)

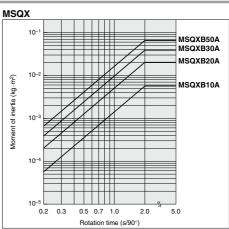
### Allowable kinetic energy and rotation time adjustment range

Set the rotation time, within stable operational guidelines, using the adjustment range specification table as detailed below. When operating at low-speeds which exceed the rotation time adjustment range, use caution as it may result in sticking or malfunction.

Model	Size	Allowable kinetic energy (J)	Stable operational rotation time adjustment range (s/90°)			
	10	0.00025	0.7 to 5			
	15	0.00039	0.7 to 5			
CRQ2X	20	0.025				
	30	0.048				
	40	0.081				
	10	0.007	1 to 5			
MSQX	20	0.025				
WISQX	30	0.048				
	50	0.081				

### **Model Selection** Select a model based on the moment of inertia and rotation time as shown graph below.





<sup>\*</sup> If the rotation time exceeds 2 s per 90°, kinetic energy is calculated with rotation time of 2 s per 90°.

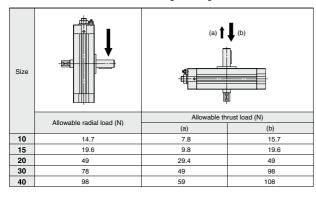


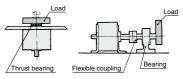
# CRQ2X/MSQX Series

### **Allowable Load**

### CRQ2X

A load up to the allowable radial/thrust load can be applied provided that a dynamic load is not generated. However, applications which apply a load directly to the shaft should be avoided whenever possible. In order to further improve the operating conditions, a method such as that shown in the drawing on the right side is recommended so that a direct load is not applied to the shaft.





### **MSQX**

Do not allow the load and moment applied to the table to exceed the allowable values shown in the table below. (Operation beyond the allowable values can cause adverse effects on service life, such as play in the table and loss of accuracy.)

Size		(a) <b>1</b>		
	Allowable radial load	Allowable th	rust load (N)	Allowable moment
	(N)	(a)	(b)	(N·m)
10	78	74	78	2.4
20	147	137	137	4.0
30	196	197	363	5.3
50	314	296	451	9.7

# Rotary Actuator Technical Data Air Consumption

Air consumption is the volume of air which is expended by the rotary actuator's reciprocal operation inside the actuator and in the piping between the actuator and the switching valve, etc. This is necessary for selection of a compressor and for calculation of its running cost.

\* The air consumption (Qcn) required for one reciprocation of the rotary actuator alone is shown in the table below, and can be used to simplify the calculation.

### Formulas

QCR = 2V x 
$$\left(\frac{P + 0.1}{0.1}\right)$$
 x 10<sup>-3</sup>  
QCP = 2 x a x L x  $\left(\frac{P}{0.1}\right)$  x 10<sup>-6</sup>  
QC = QCR + QCP

Qcn = Air consumption of rotary actuator [L (ANR)]
Qcp = Air consumption of tubing or piping [L (ANR)]
V = Internal volume of rotary actuator [cm³]
P = Operating pressure [MPa]
L = Length of piping [mm]
a = Internal cross section of piping [mm²]

**Q**c = Air consumption required for one reciprocation of rotary actuator

[L (ANR)]

When selecting a compressor, it is necessary to choose one which has sufficient reserve for the total air consumption of pneumatic actuators downstream. This is affected by factors such as leakage in piping, consumption by drain valves and pilot valves, etc., and reduction of air volume due to drops in temperature.

### **Formulas**

### Qc2 = Qc x n x Number of actuators x Reserve factor

Qc<sub>2</sub> = Compressor discharge flow rate

[L/min (ANR)]

n = Actuator reciprocations per minute Reserve factor: 1.5 or greater

Internal Cross Section of Tubing and Steel Piping

Nominal size	O.D. (mm)	I.D. (mm)	Internal cross section a (mm²)		
T□0425	4	2.5	4.9		
T□0604	6	4	12.6		
TU 0805	8	5	19.6		
T□0806	8	6	28.3		
1/8B	_	6.5	33.2		
T□1075	10	7.5	44.2		
TU 1208	12	8	50.3		
T□1209	12	9	63.6		
1/4B	_	9.2	66.5		
TS1612	16	12	113		
3/8B	_	12.7	127		
T□1613	16	13	133		
1/2B	_	16.1	204		
3/4B	_	21.6	366		
1B	_	27.6	598		

### Air Consumption

Air consumption: Qcr L (ANR)

Model	Size	Rotation angle	Internal volume					Operati	ng pressure	e (MPa)				
		(°)	<b>V</b> (cm <sup>3</sup> )	0.1	0.15	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
	10	90	1.2	_	0.006	0.007	0.009	0.012	0.014	0.016	0.018	_	_	_
	10	180	2.2	_	0.011	0.013	0.018	0.022	0.026	0.031	0.035	_	_	_
	15	90	2.9	_	0.015	0.017	0.023	0.029	0.035	0.041	0.046	_	_	_
	15	180	180 5.5	_	0.028	0.033	0.044	0.055	0.066	0.077	0.088	_	-	_
CRQ2X	20	90	7.1	0.028	0.036	0.043	0.057	0.071	0.085	0.099	0.114	0.128	0.142	0.156
UNUZX		180	13.5	0.054	0.068	0.081	0.108	0.135	0.162	0.189	0.216	0.243	0.270	0.297
	30	90	12.1	0.048	0.060	0.073	0.097	0.121	0.145	0.169	0.193	0.218	0.242	0.266
		180	23.0	0.092	0.115	0.138	0.184	0.230	0.276	0.322	0.368	0.413	0.459	0.505
	40	90	20.6	0.082	0.103	0.123	0.164	0.206	0.247	0.288	0.329	0.370	0.411	0.452
	40	180	39.1	0.156	0.195	0.234	0.313	0.391	0.469	0.547	0.625	0.703	0.781	0.859
	10		6.6	0.026	0.033	0.040	0.053	0.066	0.079	0.092	0.106	0.119	0.132	0.145
MSQX	20	190	13.5	0.054	0.068	0.081	0.108	0.135	0.162	0.189	0.216	0.243	0.270	0.297
WISUA	30	190	20.1	0.080	0.101	0.121	0.161	0.201	0.241	0.281	0.322	0.362	0.402	0.442
	50		34.1	0.136	0.171	0.205	0.273	0.341	0.409	0.477	0.546	0.614	0.682	0.750

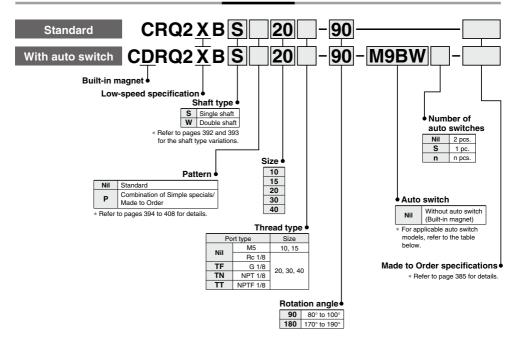


# **Low-Speed Compact Rotary Actuator Rack & Pinion Type**

# CRQ2X Series

Size: 10, 15, 20, 30, 40

### **How to Order**



Applicable Auto Switches/Refer to pages 929 to 983 for detailed auto switch specification.

0		Fig. 1	ō	140		Load volta	ge	Auto swit	ch model	Lead	wire le	ength	(m) *	Pre-wired				
Туре	Special function	Electrical entry	Indicator light	Wiring (Output)	ı	DC		Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)	5	connector	Applical	ole load		
				3-wire (NPN)		5 V. 12 V		M9NV	M9N	•	•	•	0	0	IC			
switch	_			3-wire (PNP)		5 V, 12 V		M9PV	M9P	•	•	•	0	0	circuit			
SW				2-wire		12 V		M9BV	M9B	•	•	•	0	0				
anto	Diagnostic indication			3-wire (NPN)		24 V 5 V, 12 V	5 V, 12 V	5 V 12 V		M9NWV	M9NW	•	•	•	0	0	IC	Relay,
	(2-color indicator)	Grommet	Yes	3-wire (PNP)	24 V			-	M9PWV	M9PW	•	•	•	0	0	circuit	PLC	
state	(=			2-wire		12 V		M9BWV	M9BW	•	•	•	0	0				
9	Water resistant			3-wire (NPN)		5 V. 12 V		M9NAV*1	M9NA*1	0	0	•	0	0	IC			
Solid	(2-color indicator)			3-wire (PNP)		5 V, 12 V		M9PAV*1	M9PA*1	0	0	•	0	0	circuit			
	(E color malcator)			2-wire		12 V		M9BAV*1	M9BA*1	0	0	•	0	0	-			
Reed auto switch		Grommet	Yes	3-wire (NPN equiv.)	_	_ 5 V	_	A96V	A96	•	_	•	_	_	IC circuit	_		
Be a	_	Grommet		2-wire	24 V	12 V	100 V	A93V*2	A93	•	•	•	•	_	_	Relay,		
an			No	∠-wire	24 V	12 V	100 V or less	A90V	A90	•	_	•	-	_	IC circuit	PLC		

- \*1 Although it is possible to mount water resistant type auto switches, note that the rotary actuator itself is not of water resistant construction.
- \*2 1 m type lead wire is only applicable to D-A93.
- \* Lead wire length symbols: 0.5 m ······ Nil (Example) M9NW

  1 m ····· M (Example) M9NWM

  3 m ····· I (Example) M9NWM
  - 3 m ······ L (Example) M9NWL 5 m ······ Z (Example) M9NWZ
- \* Auto switches are shipped together, (but not assembled).
- \* Auto switches marked with a "O" are produced upon receipt of orders.
- Refer to pages 970 and 971 for the details of solid state auto switch with pre-wired connector.



# Low-Speed Compact Rotary Actuator Rack & Pinion Type CRQ2X Series



### **Specifications**

Size	10	15	20	30	40				
Fluid	Air (Non-lube)								
Max. operating pressure	0.7 MPa 1 MPa								
Min. operating pressure	0.15	MPa		0.1 MPa					
Ambient and fluid temperature	0° to 60°C (No freezing)								
Cushion	Not attached								
Angle adjustment range		R	otation end ±	5°					
Rotation angle	80° to 100°, 170° to 190°								
Port size	M5 x 0.8 Rc 1/8, G 1/8, NPT 1/8, NPTF								
Output (N·m)*	0.30	0.75	1.8	3.1	5.3				

<sup>\*</sup> Output under the operating pressure at 0.5 MPa. Refer to page 381 for further information.

### Symbol





### Made to Order (Refer to pages 394 to 408 for details.)

Symbol	Specifications/Content	Applicable shaft type		
_	Shaft type variation	X,Y,Z,T,J,K		
XA1 to XA24	Shaft pattern sequencing I	S,W		
XA31 to XA59	Shaft pattern sequencing II	X,Y,Z,T,J,K		
XC7	Reversed shaft	S,W,X,T,J		
XC8 to XC11	Change of rotating range			
XC12 to XC15	Change of angle adjustable range (0° to 100°)"			
XC16, XC17	Change of angle adjustable range (90° to 190°)"	S,W,Y X*,Z*,T*,		
XC18, XC19	Change of rotating range	J <sup>*</sup> ,K <sup>*</sup>		
XC20, XC21	Change of angle adjustable range (90° to 190°)"			
Х6	Shaft and parallel key made of stainless steel	S,W,X,Y,Z, T,J,K		

<sup>\*</sup> Among the symbols XC8 to XC21, only XC12 and XC16 are compatible with shaft types X, Z, T, J and K.

# Allowable Kinetic Energy and Rotation Time Adjustment Range

Size	Allowable kinetic energy (J)	Stable operational rotation time adjustment range (s/90°)
10	0.00025	0.740.5
15	0.00039	0.7 to 5
20	0.025	
30	0.048	1 to 5
40	0.081	

Note) If operated where the kinetic energy exceeds the allowable value, this may cause damage to the internal parts and result in product failure. Please pay special attention to the kinetic energy levels when designing, adjusting and during operation to avoid exceeding the allowable limit.

### Weight

	Standard weight∗						
Size	90°	180°					
	90-	100°					
10	120	150					
15	220	270					
20	600	700					
30	900	1100					
40	1400	1600					

<sup>\*</sup> Not including the weight of auto switch.

### Moisture Control Tube IDK Series

When operating an actuator with a small diameter and a short stroke at a high frequency, the dew condensation (water droplet) may occur inside the piping depending on the conditions.

Simply connecting the moisture control tube to the actuator will prevent dew condensation from occurring. For details, refer to the Web Catalog.

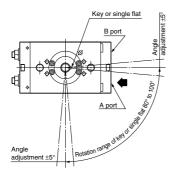


# CRQ2X Series

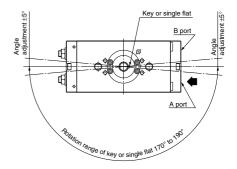
### **Rotation Range**

When pressurized from the port indicated by the arrow, the shaft will rotate in a clockwise direction.

### Rotation angle: 90°



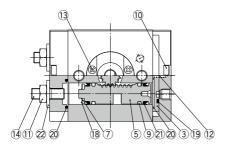
### Rotation angle: 180°



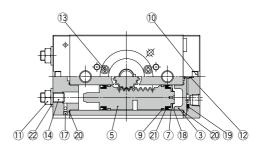
# Low-Speed Compact Rotary Actuator Rack & Pinion Type CRQ2X Series

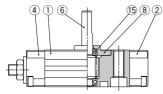
### Construction

### Standard Size 10/15



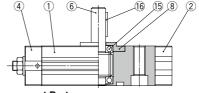
### Standard Size 20/30/40





### **Component Parts**

No.	Descrip	tion	Material
1	Body		Aluminum alloy
2	Cover		Aluminum alloy
3	Plate		Aluminum alloy
4	End cover		Aluminum alloy
5	Piston	Stainless steel	
6	Size: 10, 15	Shaft	Stainless steel
ь	Size: 20, 30, 40	Chrome molybdenum steel	
7	Seal retainer		Aluminum alloy
8	Bearing retainer		Aluminum alloy
9	Wear ring		Resin
10	Hexagon socket head of	Stainless steel	
	Size: 10, 15	Hexagon nut	Steel wire
11	Size: 20, 30, 40	Small hexagon nut	Sieel Wire



### **Component Parts**

_				
No.		Descrip	tion	Material
12	Cross recessed	screw	No. 0	Steel wire
13	Size: 10, 15	Cross r	ecessed screw No. 0	Steel wire
13	Size: 20, 30, 40	Cross	recessed screw	Steel wire
14	Hexagon socke	Chrome molybdenum steel		
15	Bearing	Bearing steel		
16	Size: 20, 30, 40	Carbon steel		
17	Size: 20, 30, 40	Steel ball	Stainless steel	
18	Type CS retaining	ng ring		Stainless steel
19	Seal			NBR
20	Gasket			NBR
21	Piston seal	-	NBR	
22	Seal washer	NBR		
23	With auto switc	_		

### **Replacement Parts**

Description				Note		
Description	10	15	20	30	40	Note
Seal kit	P473010-23	P473020-23	P473030-23	P473040-23	P473050-23	A set of above numbers 9, 19, 20, 21 and 22

### Parts included in Seal Kit

_			
No.	Description	Qty.	Note
9	Wear ring	4	
19	Seal	1	
	Gasket for cover	2	Size: 10. 15
20	Gasket for end cover	1	Size: 10, 15
	Gasket	4	Size: 20, 30, 40
21	Piston seal	4	
22	Seal washer	2	



<sup>\*</sup> A set includes all parts above.

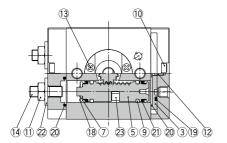
A grease pack (10 g) is included. When only a grease pack is needed, order with the following part number.

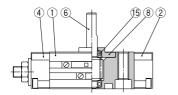
Replacement parts/Grease pack part no: P523010-21 (10 g)

# CRQ2X Series

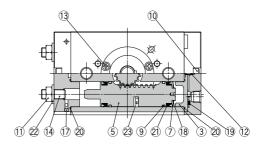
### Construction

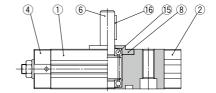
With auto switch Size 10/15



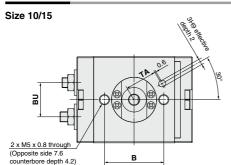


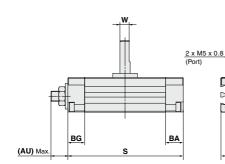
With auto switch Size 20/30/40

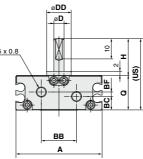




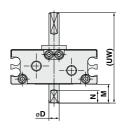
### **Dimensions**

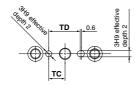












													(mm)
Size	Rotation angle	A	AU*	В	ВА	вв	вс	BF	BG	BU	D (g6)	DD (h9)	н
10	90°, 180°	42.4	(8.5)	29	8.7	17.2	6.7	2.2	8.2	16.7	5	12	18
15	90°, 180°	53.6	(9.5)	31	9.2	26.4	10.6	_	9	23.1	6	14	20

Size	Rotation angle	W	Q	S	US	UW	N	M	TA	TC	TD
10	90°	4.5	17	56.4	35	44	6	9	15.5	8	15.4
	180°	4.5		68.9			"	9			
15	90°		20	65.2	40	50		10	16	9	17.6
	180°	5.5		82.2			'				

<sup>\*</sup> The AU dimension is not the dimension at the time of shipment, since its dimension is for adjustment parts.

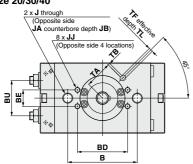
S: Upper 90°, Lower 180°

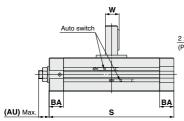


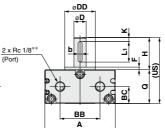
## CRQ2X Series

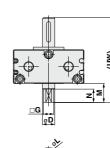
### **Dimensions**

### Size 20/30/40

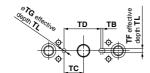








With double shaft



																			(mm)
Size	Rotation angle	Α	AU*	В	ВА	вв	вс	BD	BE	BU	D (g6)	DD (h9)	F	н	J	JA	JB	L C	к
20	90°, 180°	63	(11)	50	14	34	14.5	_	_	30.4	10	25	2.5	30	M8 x 1.25	11	6.5	_	3
30	90°, 180°	69	(11)	68	14	39	16.5	49	16	34.7	12	30	3	32	M10 x 1.5	14	8.5	M5 x 0.8 depth 6	4
40	90°, 180°	78	(13)	76	16	47	18.5	55	16	40.4	15	32	3	36	M10 x 1.5	14	8.6	M6 x 1 depth 7	5

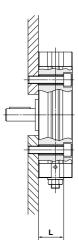
Size	Rotation	Q	s	w	Key dim	ensions	US	TA	тв	тс	TD	TF	TG	TL	uw	G	М	N	L
Size	angle	u	3	vv	b	L <sub>1</sub>	US	IA	ID	10	טו	(H9)	(H9)	''-	UW	l G	IVI	14	-
20	90°	29	104.4	115	4_0.03	00	59	24.5		13.5	27			٥.	74	8_0,1	45		9.6.01
20	180°	29	129.5	11.5	4-0.03	20	20 59	39 24.3	' '	13.5	21	4	4	2.5	74	0-0.1	15	11	9.0 -0.1
20	90°	33	122	13.5	4_0.03	20	65	27	2	19	36	_		2.5	83	10_01	18	13	11.4 0
30	180°	33	153	13.5	4-0.03	20	65	21		19	36	4	4	2.5	00	10-0.1	10	13	11.4-0.1
-40	90°	37	139.3	17	- 0	25	73	32.5	2	20	20.5	5	_	3.5		11-0.1	20	4.5	14 -01
40	180°	3/	177	17	5-0.03	25	/3	32.5	2	20	39.5	) 5	5	3.5	93	I I -0.1	20	15	14 -0.1

<sup>\*</sup> The AU dimension is not the dimension at the time of shipment, since its dimension is for adjustment parts.
\*\* In addition to Rc 1/8, G 1/8, NPT 1/8 and NPTF 1/8 are also available.

S: Upper 90°, Lower 180°

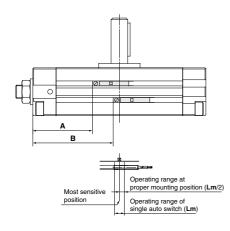
### **Unit Used as Flange Mount**

The L dimensions of this unit are shown in the below table. When hexagon socket head cap bolt of the JIS standard is used, the head of the bolt will recess into the groove of actuator.



Size	L	Screw
10	13	M4
15	16	M4
20	22.5	M6
30	24.5	M8
40	28.5	M8

### Auto Switch Proper Mounting Position (at Rotation End Detection)



		S	olid stat	e switc	h	Reed switch					
Size	Rotation angle	A	В	Operating angle (θ m)	Hystere- sis angle	А	В	Operating angle (θ <b>m</b> )	Hystere- sis angle		
10	90°	19	25.5	61°	5°	15	21.5	63°	12°		
10	180°	22	35	01	J	18	31	05	12		
15	90°	22.5	31	47°	4°	18.5	27	52°	9°		
13	180°	26.5	43.5	٦,	-	22.5	39.5	32			
20	90°	40	52.5	40°	4°	36	48.5	41°	9°		
20	180°	46	71.5	40	-	42	67.5	41	,		
30	90°	47	63	29°	2°	43	59	32°	7°		
30	180°	55	86	29°	29°		51	82	32	,	
40	90°	54	73	24°	2°	50	69	24°	5°		
40	180°	63.5	101.5		-	59.5	97.5	-4	5°		

Operating angle  $\theta m:$  Value of the operating range of single auto switch (Lm) as represented by rotation angle for shaft

Hysteresis angle: Value of the auto switch hysteresis as represented by angle

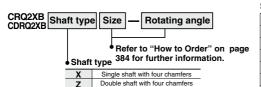
Note) Since the above values are only provided as a guideline, they are not guaranteed.

In the actual setting, adjust them after confirming the auto switch operating condition.

**SMC** 

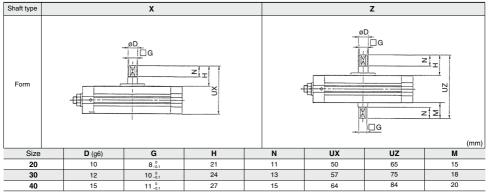
## CRQ2X Series

### 1 Shaft Type Variation, Four Chamfers (Size 20/30/40) (Dimension parts different from the standard conform to the general tolerance.) Shaft Type: X, Z

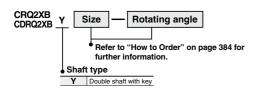


### **Specifications** Fluid Air (Non-lube) Applicable shaft type Single w/ four chamfers (X), Double w/ four chamfers (Z) Applicable size 20, 30, 40 Max. operating pressure 1.0 MPa Min. operating pressure 0.1 MPa Cushion Not attached 80° to 100°, 170° to 190° Rotation Rc 1/8, G 1/8, NPT 1/8, NPTF 1/8 Port size Auto switch Mountable

### **Dimensions**



## 2 Shaft Type Variation, Double Shaft With Key (Size 20/30/40) (Dimension parts different from the standard conform to the general tolerance.) Shaft Type: Y

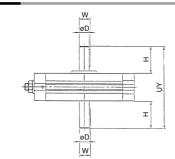


### **Specifications**

Fluid	Air (Non-lube)
Applicable shaft type	Double shaft with key (Y)
Applicable size	20, 30, 40
Max. operating pressure	1.0 MPa
Min. operating pressure	0.1 MPa
Cushion	Not attached
Rotating angle	80° to 100°, 170° to 190°
Port size	Rc 1/8, G 1/8, NPT 1/8, NPTF 1/8
Auto switch	Mountable

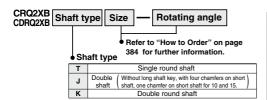
### **Dimensions**

Υ



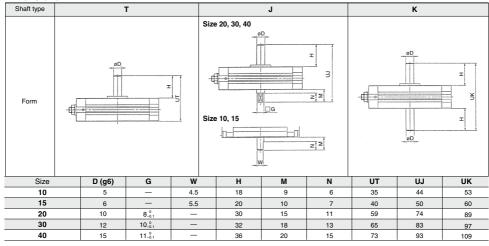
				(111111)
Size	<b>D</b> (g6)	W	Н	UY
20	10	11.5	30	89
30	12	13.5	32	97
40	15	17	36	109

### 3 Shaft Type Variation/Without Keyway (Dimension parts different from the standard conform to the general tolerance.) Shaft Type: T, J, K



Specifications							
Fluid	Air (N	on-lube)					
Applicable shaft type	Single round shaft (T), Double s	shaft (J), Double round shaft (K)					
Applicable size	10, 15	20, 30, 40					
Max. operating pressure	0.7 MPa	1.0 MPa					
Min. operating pressure	0.15 MPa	0.1 MPa					
Cushion	Not attached						
Rotating angle	80° to 100°,	170° to 190°					
Port size	M5 x 0.8	Rc 1/8, G 1/8, NPT 1/8, NPTF 1/8					
Auto switch	Mountable						

### **Dimensions**



**CRQ2X Series** (Size: 10, 15, 20, 30, 40)

# **Simple Specials:**

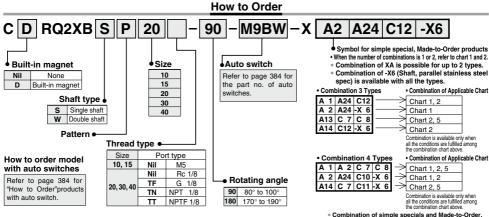
# -XA1 to -XA24: Shaft Pattern Sequencing I

Shaft shape pattern is dealt with through the Simple Specials System. Please contact your local sales representative for more details.

### Shaft Pattern Sequencing I

Symbol -XA1 to XA24

Applicable shaft type: S. W



### Combination Chart of Simple Specials for Tip End Shape

Combination of simple specials and Made-to-Order, it is possible for up to 4 types.

### Chart 1. Combination between -XA□ and -XA□ (S. W shaft)

Symbol			port	Shaf	type	Applicable																					
Syllibul			Lower	s	w	size										Con	bina	lion									
XA 1	Female thread at the end	•	1-	•	•	10, 15	XA 1					* D	)esci	ribes	the o	comi	oinati	on a	vaila	ble f	or co	rres	pond	lina s	shaft	shan	es.
XA 2	Female thread at the end	_	•	•	•	20, 30, 40	•	XA 2	]			_												9 -			
XA 3	Tip end of male thread	•	Ι-	•	•		_		XA 3																		
XA 4	Tip end of male thread	_	•	<b> </b>	•		W *	_	W*	XA 4																	
XA 5	Stepped round shaft	•	Ι-	•	•			•	-	•	XA 5																
XA 6	Stepped round shaft	_	•	<b> </b>	•		W *	_	W *	_	W*	XA 6	1														
XA 7	Round shaft with steps and male thread	•	Ι-	•	•	10, 15		•	-	•	_	•	XA 7	]													
XA 8	Round shaft with steps and male thread	_	•	<b> </b>	•	10, 15	W *	_	W *	_	W*	_	W*	XA 8	]												
XA 9	Change of the length of standard chamfered face	•	I —	•	•			•	-	•	_	•	_	•	XA 9	1											
XA10	Change of the length of standard chamfered face	_	•	<b> </b>	•		W *	_	W *	_	W*	_	W*	_	W *	XA10											
XA11	Two-sided chamfer	•	I —	•	•			•	-	•	_	•	_	•	_		XA11										
XA12	Two-sided chamfer	_	•	<b> </b>	•		W *	_	W *	_	W*	_	W*	_	W *	_	W *	XA12	]								
XA13	Shaft through-hole	•	•	•	•		_	_	-	_	_	_	_	_	•		_	_	XA13								
XA14	Shaft through-hole and female thread	•	I —	•	•	10, 15		_	-	_	_	_	_	_	•		_	_	<b> </b>	XA14							
XA15	Shaft through-hole and female thread	_	•	•	•	20, 30, 40		_	-	_	_	_	_	_	•		_	_	<b> </b>	_	XA15						
	Shaft through-hole and female thread	•	•	•	•			_	-	_	_	_	_	_	_	_	_	_	<b> </b>	_	_	XA16					
XA17	Shortened shaft	•	-	•	•	10, 15	_	•	-	•	_	•	_	•	_		_	•	•	_	•	_	XA17	1			
XA18	Shortened shaft	_	•	<b> </b>	•	10, 15, 20, 30, 40	W *	_	W *	_	W*	_	W *	_	W *	_	W *	_	W *	w *	_	_	w *	XA18	1		
XA19	Shortened shaft	•	•	<b> </b>	•	10, 15	_	_	-	_	_	_	_	_	_	_	_	_	W *	_	_	_	_	I —	1		
XA20	Reversed shaft	•	•	•	•	10, 15, 20, 30, 40	_	_	-	_	_	_	_	_	_	_	_	_	•	_	_	_	_	I —	XA20		
XA21	Stepped round shaft with double-sided chamfer	•	-	•	•		_	•	-	•	_	•	_	•	_	•	_	•	<b> </b>	_	_	_	_	•	•	XA21	
XA22	Stepped round shaft with double-sided chamfer	_	•	<b> </b> —	•	10, 15	W*	_	W*	_	W*	_	w*	_	w*	_	W*	_	<b> </b> —	_	_	_	w*	<b>—</b>	-	w *	XA2
XA23	Right-angle chamfer	•	<b>—</b>	•	•		•	•	_	•	_	•	_	•	_	•	_	•	•	•	•	•	_	•	•	_	•
XA24	Double key	•	<b>—</b>	•	•	20, 30, 40	•	•	_	_	_		_	_	_	_	_	_	•	•	•	•	_		•	_	Ξ

### **Combination Chart of Made to Order**

### Chart 2. Combination between -XA□ and -XC□ (Made to Order/ Details of -XC□, refer to page 404.)

Symbol	Description	Applicable	licable Combination Symbol Description Ap		Applicable	Combination	
Syllibul	Description	size	XA1 to XA24	Joyilloui	Description	size	XA1 to XA24
XC 7	Reversed shaft		-	XC18	Channel of antaking and a		•
XC 8			•	XC19	Change of rotating range	20, 30, 40	•
XC 9 XC10	Change of rotating range		•	XC20	Change in angle adjustable	20, 30, 40	•
XC10	Change of rotating range		•	XC21	range 90° to 190°		•
XC11		10, 15	•				
XC12		20, 30, 40	•				
XC13	Change in angle adjustable	.,,	•				
			•				
XC15			•	1			
XC16	Change in angle adjustable		•	]			
XC17	range 90° to 190°		•	] * Ch	art 5. Refer to page 404 for co	mbination availat	ole between -XC∟
301							

### **Shaft Pattern Sequencing I**

Symbol

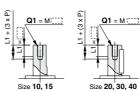
-XA1 to XA8

### **Additional Reminders**

- 1. Enter the dimensions within a range that allows for additional machining.
- 2. Unless indicated otherwise, the dimensional tolerance conforms to the general tolerance. SMC will make appropriate arrangements.
- 3. The length of the unthreaded portion is 2 to 3 pitches.
- 4. Unless specified otherwise, the thread pitch is based on coarse metric threads. M3 x 0.5, M4 x 0.7, M5 x 0.8
  - M6 x 1
- 5. Enter the desired figures in the [\_\_\_\_ portion of the diagram.
- 6. XA1 to XA24 are the standard products that have been additionally machined.
- 7. Chamfer face of the parts machining additionally is C0.5.

### Symbol: A1

Machine female threads into the long shaft. The maximum dimension L1 is, as a rule, twice the thread size (Example) For M3: L1 = 6 Applicable shaft types: S, W



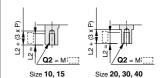
	Ť
	Size
(mm)	
	(mm)

### Symbol: A2

Machine female threads into the short shaft.

The maximum dimension L2 is, as a rule, twice the thread size. (Example) For M4: L2 = 8





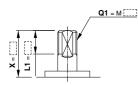
	(mm)
Size	Q2
10	M3
15	M3, M4
20	M3, M4
30	M3, M4, M5
40	M4, M5, M6

### Symbol: A3

The long shaft can be further shortened by machining male threads into it.

(If shortening the shaft is not required, indicate "\*" for dimension X.)

Applicable shaft types: S, W



			(mm)
Size	Х	L1 max	Q1
10	9 to 18	X – 4	M5
15	10 to 20	X – 4	M6

### Symbol: A4

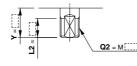
Size

The short shaft can be further shortened by machining male threads into it.

(If shortening the shaft is not required, indicate "\*" for dimension Y.)

Applicable shaft type: W

M4, M5, M6



			(mm)
Size	Υ	L2 max	Q2
10	7 to 9	Y-2	M5
15	8 to 10	Y-3	M6

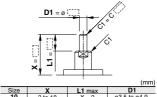
### Symbol: A5

The long shaft can be further shortened by machining it into a stepped round shaft.

(If shortening the shaft is not required, indicate "\*" for dimension X.) (If not specifying dimension C1, indicate "\*" instead.)

· Applicable shaft types: S, W

Equal dimensions are indicated by the same marker.



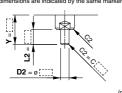
Size	Х	L1 max	D1
10	3 to 18	X-2	ø3.5 to ø4.9
15	3 to 20	X-2	ø3.5 to ø5.9

### Symbol: A6

The short shaft can be further shortened by machining it into a stepped round shaft.

(If shortening the shaft is not required, indicate "\*" for dimension Y.) (If not specifying dimension C2, indicate "\*" instead.)

· Applicable shaft type: W . Equal dimensions are indicated by the same marker.

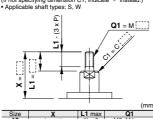


			(11111)
Size	Y	L2 max	D2
10	1 to 9	Y	ø3.5 to ø4.9
15	1 to 10	Y	ø3.5 to ø5.9

### Symbol: A7

The long shaft can be further shortened by machining it into a stepped round shaft with male threads. (If shortening the shaft is not required, indicate "\*" for dimension X.)

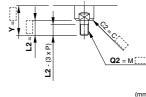
(If not specifying dimension C1, indicate "\*" instead.)



### Symbol: A8

The short shaft can be further shortened by machining it into a stepped round shaft with male thread (If shortening the shaft is not required, indicate "\*" for dimension Y.)

(If not specifying dimension C2, indicate "\*" instead.) · Applicable shaft type: W



			(mm
Size	Υ	L2 max	Q2
10	6 to 9	Y	M3, M4
15	7.5 to 10	Y	M3, M4, M5

9.5 to 20

### Shaft Pattern Sequencing I

Symbol

### -XA9 to XA16

### **Additional Reminders**

- 1. Enter the dimensions within a range that allows for additional machining.
- 2. Unless indicated otherwise, the dimensional tolerance conforms to the general tolerance. SMC will make appropriate arrangements.
- 3. The length of the unthreaded portion is 2 to 3 pitches
- 4. Unless specified otherwise, the thread pitch is based on coarse metric threads.

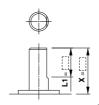
M3 x 0.5, M4 x 0.7, M5 x 0.8 M6 x 1

- 5. Enter the desired figures in the [\_\_\_\_ portion of the diagram.
- 6. XA9 to XA24 are the standard products that have been additionally machined
- 7. Chamfer face of the parts machining additionally is C0.5.

### Symbol: A9

The long shaft can be further shortened by changing the length of the standard chamfer on the long shaft side. (If shortening the shaft is not required, indicate "\*" for dimension X.)

Applicable shaft types: S, W



			(mm)
ı	Size	Х	L1
Ī	10	8 to 18	{10 - (18 - X) } to (X - 2)
	15	10 to 20	{10 - (20 - X) } to (X - 2)

### Symbol: A10

The short shaft can be further shortened by changing the length of the standard chamfer.

(If shortening the shaft is not required, indicate "\*" for dimension Y.)

Applicable shaft type: W

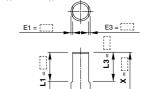


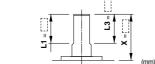
		(11111)
Size	Y	L2
10	3 to 9	6-(9-Y) to Y
15	3 to 10	7-(10-Y) to Y

### Symbol: A11

The long shaft can be further shortened by machining a double-sided chamfer on to it.

- Since L1 is a standard chamfer, dimension E1 is 0.5 or more
- (If altering the standard chamfer and shortening the shaft are not required, indicate "\*" for both the L1 and X dimensions.) · Applicable shaft types: S, W





### Symbol: A12

The short shaft can be further shortened by machining a double-sided chamfer on to it.

- Since L2 is a standard chamfer, dimension E2 is 0.5 or more
- (If altering the standard chamfer and shortening the shaft are not required, indicate "\*" for both the L2 and Y dimensions.)

· Applicable shaft type: W

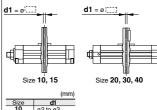


### Symbol: A13

Shaft with through-hole

Minimum machining diameter for d1 is 0.1.

Applicable shaft types: S, W

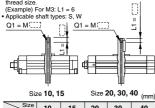


	(111111)
Size	d1
10	ø2 to ø3
15	ø2 to ø4
20	ø2.5 to ø3.5
30	ø3 to ø5.5
40	ø4 to ø7

### Symbol: A14

A special end is machined onto the long shaft, and a through-hole is drilled into it. Female threads are machined into the through-hole, whose diameter is equivalent to the pilot hole diameter.

 The maximum dimension L1 is, as a rule, twice the thread size



ø3.3 ø3.3 ø3.3

10 15 20 30 40

ø2.5 ø2.5 ø2.5

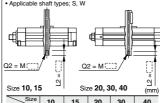
L3 max

ø4.2

ø4.2

A special end is machined onto the short shaft, and a through-hole is drilled into it. Female threads are machined into the through-hole, whose diameter is equivalent to the pilot hole diameter.

- The maximum dimension L2 is, as a rule, twice the thread size. (Example) For M4: L2 = 8
- · Applicable shaft types; S, W



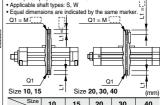
Size 10, 1	•	Siz	ze <b>20,</b> 3	0, 40	(mm)
Size	10	15	20	30	40
M3 x 0.5	ø2.5	ø2.5	ø2.5	_	
M4 x 0.7	_	ø3.3	ø3.3	ø3.3	_
M5 x 0.8	_	_	_	ø4.2	ø4.2
M6 x 1	_	_	_		ø5

### Symbol: A16

A special end is machined onto both the long and short shafts, and a through-hole is drilled into both shafts. Female threads are machined into the through-holes, whose diameter is equivalent to the diameter of the pilot holes.

• The maximum dimension L1 is, as a rule, twice the thread

size. (Example) For M5: L1 = 10



Size	10	15	20	30	40
M3 x 0.5	ø2.5	ø2.5	ø2.5	_	_
M4 x 0.7	_	ø3.3	ø3.3	ø3.3	_
M5 x 0.8	_	_	_	ø4.2	ø4.2
M6 x 1	_	_		_	ø5

Thread M3 x 0.5

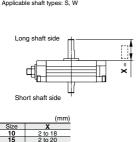
M4 x 0.7

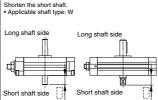
M5 x 0.8 M6 x 1

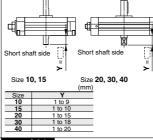
### **Shaft Pattern Sequencing I**

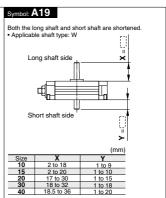
Symbol -XA17 to XA24









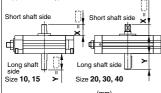


### Symbol: A20

30

Reverse the assembly of the shaft. (Thus shortening the long end and the short end of the shaft.) (If shortening the shaft is not required, indicate "\*" for

dimension X and Y.) Applicable shaft types: S, W



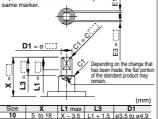
		(mm)
Size	X	Y
10	2 to 10	1 to 17
15	2 to 11	1 to 19
20	2.5 to 16.5	16 to 28.5
30	3 to 20	16 to 30
40	3 to 22	16.5 to 34

### Symbol: A21

Symbol: A18

The long shaft can be further shortened by machining it into a stepped round shaft with a double-sided chamfer. (If shortening the shaft is not required, indicate "\*" for

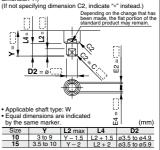
dimension X.)(If not specifying dimension C1, indicate \*" instead.) · Applicable shaft types: S, W . Equal dimensions are indicated by the



5.5 to 20 X - 4 L1 + 2 Ø3.5 to Ø5.9

### Symbol: A22

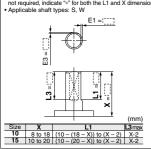
The short shaft can be further shortened by machining it into a stepped round shaft with a double-sided chamfer. (If shortening the shaft is not required, indicate "\*" for dimension Y



### Symbol: A23

The long shaft can be further shortened by machining right-angle double-sided chamfer onto it.

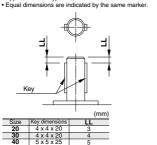
 Since L1 is a standard chamfer, dimension E1 is 0.5 or more. (If altering the standard chamfer and shortening th shaft are not required, indicate "\*" for both the L1 and X dimensions.)



### Symbol: A24

Keys and keyways are machined at 180° from the standard position

· Applicable shaft types: S, W



**CRQ2X Series** (Size: 10, 15, 20, 30, 40)

# Simple Specials:

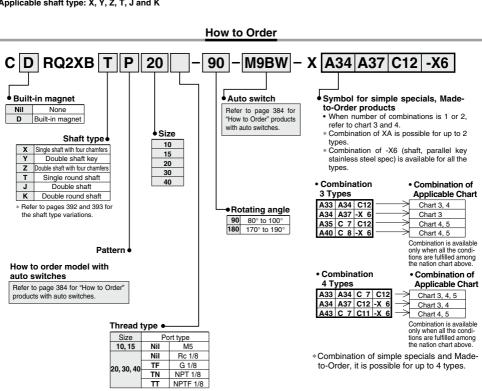
# -XA31 to -XA59: Shaft Pattern Sequencing II

Shaft shape pattern is dealt with through the Simple Specials System. Please contact your local sales representative for more details.

### **Shaft Pattern Sequencing II**

Symbol -XA31 to XA59

Applicable shaft type: X, Y, Z, T, J and K



Symbol

### **Shaft Pattern Sequencing II**

-XA31 to XA59

### Combination Chart of Simple Specials for Tip End Shape

Chart 3. Combination between -XA□ and -XA□ (X, Y, Z, T, J, K shafts)

Symbol	Description	Тор	port			Shaft	type			Applicable					Camb	oinatio	_						
Symbol	Description	Upper	Lower	J	K	Т	Х	Υ	Z	size					COME	mauc	)[]						
XA31	Female thread at the end	•	_	_	_	_	_	•	_	20, 30, 40	XA31						* C	orresi	pondi	ng sh	afts tv	vne	
XA32	Female thread at the end	_	•	_	_	_	_	•	_	20, 30, 40	Y *	XA32	1							comb			
XA33	Female thread at the end	•	_	•	•	•	_	_	_	10, 15,	_	_	XA33				_						
XA34	Female thread at the end	_	•	_	•	•	•	_	_	20, 30, 40	_	_	K, T *	XA34									
XA35	Female thread at the end	•	_	_	_	_	•	_	•	20, 30, 40	_	_	<b>—</b>	X *	XA35	]							
XA36	Female thread at the end	_	•	•	_	_	_	_	•	20, 30, 40	_	_	J*	_	Z *	XA36							
XA37	Stepped round shaft	•		•	•	•	_	_	_	10, 15,	_	-	-	KT*	_	J*	XA37						
XA38	Stepped round shaft	_	•	_	•	_	_	_	_	20, 30, 40	_	_	K*	_	_	_	K *	1					
XA39	Shaft through hole	•	•	_	_	_	_	•	_	20, 30, 40	_	_	I —	_	_	<u> </u>	_						
XA40	Shaft through hole	•	•	_	•	•	_	_	_	10, 15,	_	-	_	_	_	_	-						
XA41	Shaft through hole	•	•	•	_	1	•	1	•	20, 30, 40	_	_	l –	_	_	<b>—</b>	1						
XA42	Shaft through hole and female thread	•	•	_	_	_	_	•	_	20, 30, 40	<b>—</b>	_	—	_	_	<del>-</del>	_						
XA43	Shaft through hole and female thread	•	•	_	•	•	_	-	_		_	-	_	_	_	_	-						
XA44	Shaft through hole and female thread	•	•	•	_	-	•	1	•	10, 15,	_	_	l –	_	_	-	1	XA38					
XA45	Middle-cut chamfer	•	_	•	•	•	_	_	_	20, 30, 40	_	_	—	K *	_	J*	_	K *	XA39	XA40	XA41	XA45	
XA46	Middle-cut chamfer	-	•	_	•	_	-	-	_		_	-	K *	_	_	_	K *	_	_	-	_	K *	XA46
XA48	Change of long shaft length	•	_	_	_	-	-	•	_		_	Y *	Υ*	_	_	-	1	—	Y *	_	_	_	[ — ]
XA49	Change of short shaft length	_	•	_	_	-	-	•	_	20, 30, 40	Y *	_	-	_	_	<b> </b>	_	_	Y *	_	_	_	-
XA50	Change of double shaft length	•	•	_	_	_	-	•	_		_	-	-	_	_	_	-	_	Y *	_	_	_	_
XA51	Change of long shaft length	•	_	•	•	•	ı	ı	1	10, 15,	_	_		K, T *	_	J *	ı	K *	_	K, T *	_	_	K*
XA52	Change of short shaft length	_	•	_	•	-	-	_	_	20, 30, 40	_	_	K *	_	_	<b>—</b>	K *	_	_	K *	_	K, T *	-
XA53	Change of double shaft length	•	•	_	•	-	-	-	-	20, 30, 40	_	_	-	_	_	_	-	_	_	K *	_	_	_
XA54	Change of long shaft length	•	_	ı	_	ı	•	ı	•		_	_	-	X *	_	Z *	ı	-	_	_	X, Z *	_	
XA55	Change of short shaft length	_	•	•	_	1	1	ı	•	20, 30, 40		_	J *	_	Z *	_	*	-	_	_	J, Z *	_	J*
XA56	Change of double shaft length	•	•	_	_	_	_	_	•		_	_			_		_	_		_	Z *	_	
XA57	Change of double shaft length	•	•	•	_	-	-	_	_	10, 15,	_	_	<b>—</b>	_	_	-	-	_	_	_	J*	_	_
XA58	Reversed shaft, Change of double shaft length	•	•	•	_	•	1			20, 30, 40	_	_	-	_		_		-	_	T *	J *		_
XA59	Reversed shaft, Change of double shaft length	•	•	_	_	_	•	_	_	20, 30, 40	-	_	-	_	_	-	_	_	_	_	X *		

### **Combination Chart of Made to Order**

Chart 4. Combination between -XA□ and -XC□ (Made to Order/Details of -XC□, refer to page 404.)

			Combination
Symbol	Description	Applicable size	XA31 to XA59
XC 7	Reversed shaft		_
XC 8			•
XC 9	Change of rotating range		•
XC10	Change of rotating range		•
XC11		10, 15,	•
XC12		20, 30, 40	•
XC13	Change in angle adjustable range 0° to 100°	20, 30, 40	•
XC14	Change in angle adjustable range 0 to 100		•
XC15			•
XC16	Change in angle adjustable range 90° to 190°		•
XC17	Change in angle adjustable range 30 to 130		•
XC18	Change of rotating range		•
XC19	Change of folding failige	20, 30, 40	•
XC20	Change in angle adjustable range 90° to 190°	20, 00, 10	•
XC21	onange in angle adjustable range 50° to 150		•

<sup>\*</sup> Chart 5. Refer to page 404 for combination available between -XC  $\!\square$  and -XC  $\!\square$  .

Symbol

### -XA31 to XA38

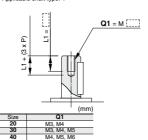
### **Shaft Pattern Sequencing II**

### **Additional Reminders**

- 1. Enter the dimensions within a range that allows for additional machining.
- 2. Unless indicated otherwise, the dimensional tolerance conforms to the general tolerance. SMC will make appropriate arrangements.
- 3. The length of the unthreaded portion is 2 to 3
- 4. Unless specified otherwise, the thread pitch is based on coarse metric threads. M3 x 0.5, M4 x 0.7, M5 x 0.8 M6 x 1
- 5. Enter the desired figures in the [\_\_\_] portion of the diagram.
- 6. XA31 to XA59 are the standard products that have been additionally machined.
- 7. Chamfer face of the parts machining additionally is C0.5.

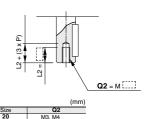
### Symbol: A31

- Machine female threads into the long shaft The maximum dimension L1 is, as a rule, twice the thread size (Example) For M3: L1 = 6
- Applicable shaft type: Y



### Symbol: A32

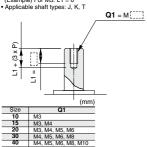
- Machine female threads into the short shaft. • The maximum dimension L2 is, as a rule,
- twice the thread size (Example) For M4: L2 = 8
- Applicable shaft type: Y



Size	Q2
20	M3, M4
30	M3, M4,M5
40	M4, M5,M6

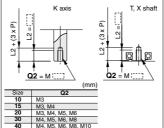
### Symbol: A33

- Machine female threads into the long shaft. . The maximum dimension L1 is, as a rule,
- twice the thread size.
- (Example) For M3: L1 = 6



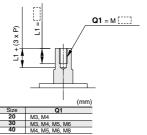
### Symbol: A34

- Machine female threads into the short shaft. The maximum dimension L2 is, as a rule. twice the thread size.
- (Example) For M5: L2 = 10
- · Applicable shaft types: K. T. X



### Symbol: A35

- Machine female threads into the long shaft. The maximum dimension I 1 is as a rule. twice the thread size.
- (Example) For M3: L1 = 6
- Applicable shaft types: X. Z

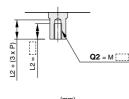


	(11111)
Size	Q1
20	M3, M4
30	M3, M4, M5, M6
40	M4, M5, M6, M8

### Symbol: A36

- Machine female threads into the short shaft. • The maximum dimension L2 is, as a rule, twice the thread size
- (Example) For M4: L2 = 8 Applicable shaft types: J, Z





Size	Q2
20	M3, M4
30	M3, M4, M5, M6
40	M4, M5, M6, M8

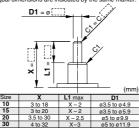
### Symbol: A37

The long shaft can be further shortened by machining into a shart can be further sinderled by interning the shaft is not required, indicate "\*" for dimension X.) (If not specifying dimension C1, indicate "\*" instead.)

• Applicable shaft types: J, K, T

4 to 32

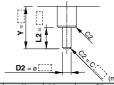
Equal dimensions are indicated by the same marker



### Symbol: A38

The short shaft can be further shortened by machining it into a stepped round shaft. (If shortening the shaft is not required, indicate "\*" for

- dimension Y.)
  (If not specifying dimension C2, indicate "\*" instead.)
- Applicable shaft type: K
   Equal dimensions are indicated by the same marker.



Size	Y	L2 max	D2
10	1 to 18	Y	ø3.5 to ø4.9
15	1 to 20	Y	ø3.5 to ø5.9
20	1 to 30	Y	ø5 to ø 9.9
30	1 to 32	Y	ø5 to ø11.9
40	1 to 36	Y	ø5 to ø14.9

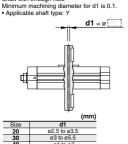
### **Shaft Pattern Sequencing II**

Symbol

### -XA39 to XA48



Shaft with through-hole

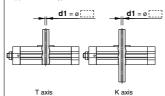


### Symbol: A40

Shaft with through-hole

Minimum machining diameter for d1 is 0.1.

• Applicable shaft types: K, T

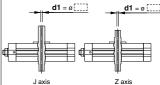


d1
ø2 to ø3
ø2 to ø4
ø2.5 to ø6
ø3 to ø8
ø4 to ø10

### Symbol: A41

Shaft with through-hole

Minimum machining diameter for d1 is 0.1. Applicable shaft types: J, X, Z

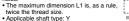


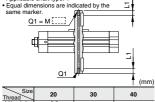
	(11111)
Size	d1
10	ø2 to ø3
15	ø2 to ø4
20	ø2.5 to ø5
30	ø3 to ø7
40	ø4 to ø8

### Symbol: A42

A special end is machined onto both the long and short shafts, and a through-hole is drilled into both shafts. Female threads are machined into the through-holes

whose diameter is equivalent to the diameter of the pilot





			(mm)
Size	20	30	40
M3 x 0.5	ø2.5	_	
M4 x 0.7	ø3.3	ø3.3	_
M5 x 0.8	_	ø4.2	ø4.2
M6 x 1	_	_	ø5

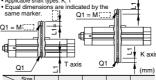
### Symbol: A43

A special end is machined onto both the long and short shafts, and a through-hole is drilled into both shafts. Female threads are machined into the through-holes

whose diameter is equivalent to the diameter of the pilot holes • The maximum dimension L1 is, as a rule,

twice the thread size.

• Applicable shaft types: K, T



<u>Q1</u> /					(mm)
Size	10	15	20	30	40
M 3 x 0.5	ø2.5	ø2.5	ø2.5	_	_
M 4 x 0.7	_	ø3.3	ø3.3	ø3.3	_
M 5 x 0.8	-	_	ø4.2	ø4.2	ø4.2
M 6 x 1	-	_	ø5	ø5	ø5
M 8 x 1.25	-	_	_	ø6.8	ø6.8
M10 x 1.5	_	_	_	_	ø8.5

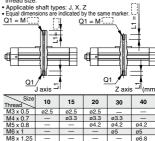
### Symbol: A44

A special end is machined onto both the long and short shafts, and a through-hole is drilled into both shafts. Female threads are machined into the through-holes

whose diameter is equivalent to the diameter of the pilot holes.

The maximum dimension L1 is, as a rule, twice the

thread size



read	10	15	20	30	40	
7.0 x 8N	ø2.5	ø2.5	ø2.5	_	-	
14 x 0.7	_	ø3.3	ø3.3	ø3.3	_	
15 x 0.8	_	_	ø4.2	ø4.2	ø4.2	
/16 x 1	_	_	_	ø5	ø5	
18 x 1.25	_	_	_	_	ø6.8	

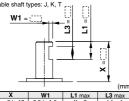
### Symbol: A45

The long shaft can be further shortened by machining a middle-cut chamfer into it.

(If shortening the shaft is not required, indicate "\*' for dimension X.)

(The position is that of the standard flat at the keyway

· Applicable shaft types: J, K, T



				(111111)
Size	Х	W1	L1 max	L3 max
10	6 to 18	0.5 to 1.5	X – 2	L1 – 1
15	6.5 to 20	0.5 to 1.5	X – 2	L1 – 1
20	9.5 to 30	1 to 2	X - 2.5	L1 – 2
30	11.5 to 32	1 to 2	X – 3	L1 – 2
40	12.5 to 36	1 to 2	X – 3	L1 – 2

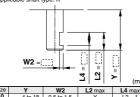
### mbol: A46

The short shaft can be further shortened by machining a middle-cut chamfer into it.

(If shortening the shaft is not required, indicate "\*" for dimension Y.)

(The position is that of the standard flat at the keyway

· Applicable shaft type: K

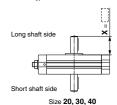


l			1 1	' (111111)
Size	Υ	W2	L2 max	L4 max
10	4 to 18	0.5 to 1.5	Y	L2 - 1
15	4.5 to 20	0.5 to 1.5	Y	L2 - 1
20	6.5 to 30	1 to 2	Y	L2 - 2
30	8.5 to 32	1 to 2	Y	L2 - 2
40	9.5 to 36	1 to 2	Y	L2 - 2

### Symbol: A48

Shorten the long shaft.

· Applicable shaft type: Y

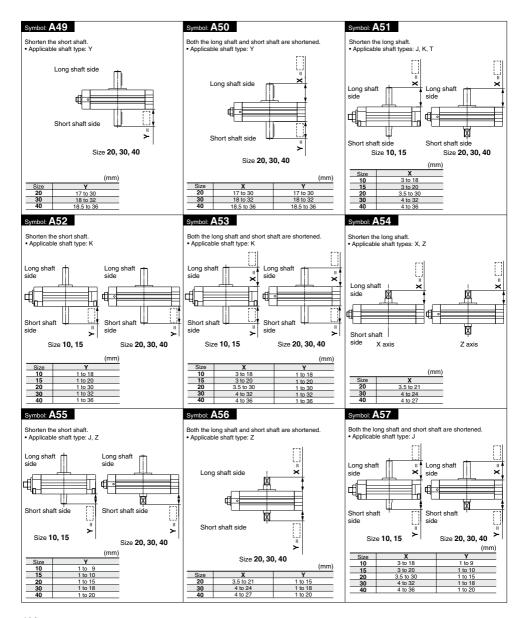


	(mm)
Size	X
20	17 to 30
30	18 to 32
40	18.5 to 36

### **Shaft Pattern Sequencing II**

Symbol

-XA49 to XA57

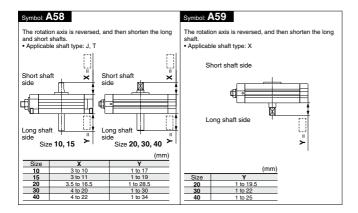


# Simple Specials CRQ2X Series

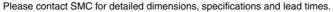
Symbol

## **Shaft Pattern Sequencing II**

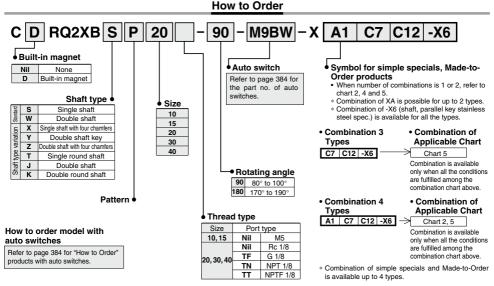
-XA58 to XA59



# CRQ2X Series Made to Order Specifications 1





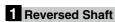


### **Combination Chart of Made to Order**

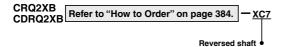
### Chart 5. Combination between -XC□ and -XC□

Symbol	Description	Applicable size	Combination
XC7	Reversed shaft		XC 7
XC8			
to	Change of rotating range		•
XC11			
XC12		10, 15,	
to	Change in angle adjustable range 0° to 100°	20, 30, 40	•
XC15			
XC16	Change in angle adjustable range 90° to 190°		
XC17	Officinge in angle adjustable range 30 to 130		
XC18	Change of rotating range		
XC19	Change of folding range	20, 30, 40	
XC20	Change in angle adjustable range 90° to 190°	∠0, 30, 40	•
XC21	Change in angle adjustable range 30 to 130		



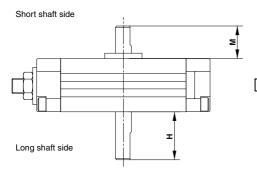


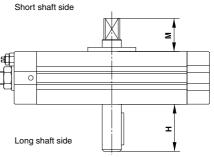
Symbol -XC7



### **Specifications**

Applicable size	10, 15, 20, 30, 40
Applicable shaft type	S, W, X, T, J shaft





Size 10, 15

		(mm)
Size	М	Н
10	10	17 (—)*
15	11	19 (—)*
20	16.5	28.5 (19.5)*
30	20	30 (22)*
40	22	34 (25)*

\* For X shaft

Size 20, 30, 40

# **CRQ2X Series Made to Order Specifications 2**

Please contact SMC for detailed dimensions, specifications and lead times.



# 2 Change of Rotating Range

-XC8 to XC11, XC18/XC19



Specifications
Applicable shaft type S, W, Y

Symbol -XC8 to XC11, XC18/XC19

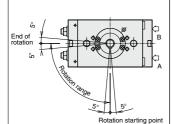
### Additional Reminders

The rotation starting point shows the positions of one flat chamfering and the key groove when pressurized to the connecting port (B).

### Symbol: C8

Angle adjustment at the rotation starting point and the end point are at  $\pm 5^{\circ}$ . Rotating range is changed. Rotation angle is at  $90^{\circ} \pm 10^{\circ}$ 

Rotating range is changed. Rotation angle is at 90° ±10° The rotation starting point is on the perpendicular line (down).

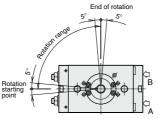


The figure shows the view from the long shaft end.

### Symbol: C9

Angle adjustment at the rotation starting point and the end point are at  $\pm 5^{\circ}$ . Rotating range is changed. Rotation angle is at  $90^{\circ} \pm 10^{\circ}$ .

Rotating range is changed. Rotation angle is at 90° ±10' The rotation starting point is on the horizontal line (left).



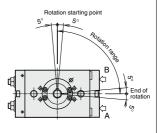
The figure shows the view from the long shaft end.

### Symbol: C10

Angle adjustment at the rotation starting point and the end point are at ±5°.

Rotating range is changed. Rotation angle is at 90° ±10°.

Rotating range is changed. Rotation angle is at 90° ±10°. The rotation starting point is on the perpendicular line (up).

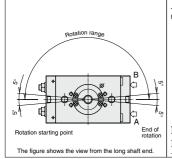


The figure shows the view from the long shaft end.

### Symbol: C11

Angle adjustment at the rotation starting point and the end point are at  $\pm 5^{\circ}$ .

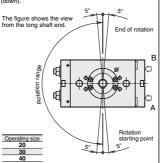
Rotating range is changed. Rotation angle is at 180° ±10' The rotation starting point is on the horizontal line (left).



### Symbol: C18

Angle adjustment at the rotation starting point and the end point are at  $\pm 5^{\circ}$ .

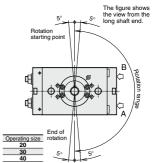
Rotating range is changed. Rotation angle is at  $180^\circ\pm10^\circ$  The rotation starting point is on the perpendicular line



### Symbol: C19

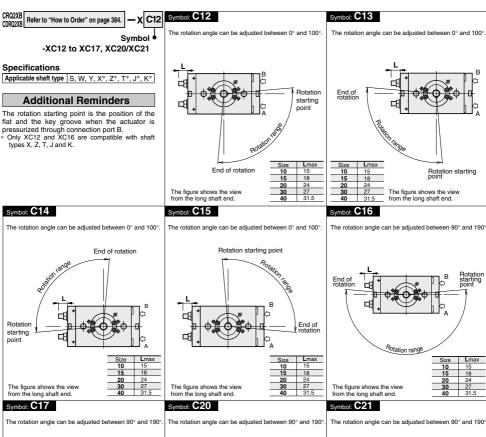
Angle adjustment at the rotation starting point and the end point are at  $\pm 5^{\circ}.$ 

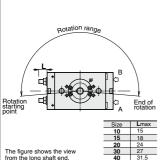
Rotating range is changed. Rotation angle is at  $180^{\circ} \pm 10^{\circ}$ . The rotation starting point is on the perpendicular line (up)



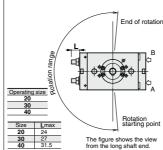
# 3 Change of Angle Adjustable Range (0° to 100°, 90° to 190°)

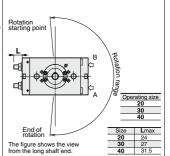
Symbol -XC12 to XC17, XC20/XC21





from the long shaft end.



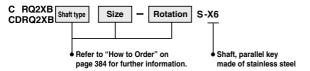


# CRQ2X Series Made to Order Specifications 3 Please contact SMC for detailed dimensions, specifications and lead times.



# 4 Shaft, Parallel Key Made of Stainless Steel Spec.

Symbol



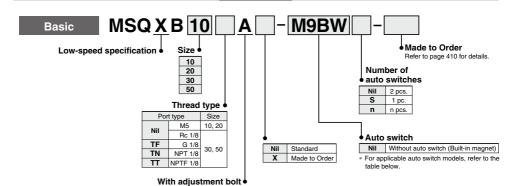
Stainless steel is used as a substitute material for standard parts when used under conditions with a possibility of oxidization or decay.

Fluid	Air (Non-lube)
Applicable shaft type	S, W, X, Y, Z, T, J, K
Applicable size	20, 30, 40
Max. operating pressure	1.0 MPa
Min. operating pressure	0.1 MPa
Cushion	Not attached
Rotation range	80° to 100°, 170° to 190°
Stainless steel part	Shaft, Parallel key
Port size	Rc 1/8, G 1/8, NPT 1/8, NPTF 1/8
Auto switch	Mountable

# Low-Speed Rotary Table Rack & Pinion Type **MSQX Series**

Size: 10, 20, 30, 50

### **How to Order**



### Applicable Auto Switches/Refer to pages 929 to 983 for detailed auto switch specification.

o o		Electrical	ō	\A/:i	Wiring Load vo			Auto swit	ch model	Lead	wire le	ngth	(m) *	Pre-wired											
Туре	Special function	entry	Indicator light	(Output)		DC	AC	Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)	5 (Z)	connector	Applica	ole load									
				3-wire (NPN)		5 V. 12 V		M9NV	M9N	•	•	•	0	0	IC										
switch	_			3-wire (PNP)		5 V, 12 V		M9PV	M9P	•	•	•	0	0	circuit										
SWİ				2-wire		12 V	1	M9BV	M9B	•	•	•	0	0	_										
anto	Diagnostic indication			3-wire (NPN)	24 V 5 V, 12	EV 10	5 V 40 V	5 V 40 V	5 V 40 V		M9NWV	M9NW	•	•	•	0	0	IC	Delevi						
a B	(2-color indicator)	Grommet	Yes 3	3-wire (PNP)		3 V, 12 V	_	M9PWV	M9PW	•	•	•	0	0	circuit	Relay, PLC									
state	(2 color maloator)			2-wire		12 V	1	M9BWV	M9BW	•	•	•	0	0	_	1 20									
													3-wire (NPN)	re (NPN)	5 V. 12 V		M9NAV*1	M9NA*1	0	0	•	0	0	IC	
Solid	Water resistant (2-color indicator)			3-wire (PNP)		5 V, 12 V		M9PAV*1	M9PA*1	0	0	•	0	0	circuit										
	(2-color indicator)			2-wire		12 V	1	M9BAV*1	M9BA*1	0	0	•	0	0	_										
Reed auto switch		C	Yes	3-wire (NPN equiv.)	_	5 V	_	A96V	A96	•	_	•	-	_	IC circuit	_									
P S	_	Grommet		2-wire	24 V	12 V	100 V	A93V*2	A93	•	•	•	•	_	_	Relay,									
al			No	2-wire	24 V	12 V	100 V or less	A90V	A90	•	_	•	-		IC circuit	PLC									

- \*1 Although it is possible to mount water resistant type auto switches, note that the rotary actuator itself is not of water resistant construction.
- \*2 1 m type lead wire is only applicable to D-A93.
- \* Lead wire length symbols: 0.5 m ······ Nil (Example) M9NW 1 m ····· M (Example) M9NWM
  - 3 m ····· L (Example) M9NWL 5 m ····· Z (Example) M9NWZ
- \* Auto switches are shipped together, (but not assembled).
- \* Auto switches marked with a "O" are produced upon receipt of orders.
- \* Refer to pages 970 and 971 for the details of solid state auto switch with pre-wired connector.

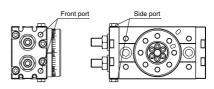
# **MSQX** Series



### **Specifications**

Size	e	10	20	30	50			
Fluid		Air (Non-lube)						
Max. operating	pressure	1 MPa						
Min. operating	pressure	0.1 MPa						
Ambient and flui	d temperature	0° to 60°C (No freezing)						
Cushion		Not attached						
Angle adjustme	ent range		0 to	190°				
Maximum rotat	ion angle		19	90°				
Port size	End port	M5 x 0.8 Rc 1/8, G 1/8, NPT 1/8, NPTF 1						
Port Size	Side port	M5 x 0.8						
Output (N·m)*		0.89 1.8 2.7 4.6						

<sup>\*</sup> Output under the operating pressure at 0.5 MPa. Refer to page 381 for further information.



### Symbol





### Made to Order

Refer to page 416 for details.

Symbol	Specifications/Content
-X15□	With external stopper

# Allowable Kinetic Energy and Rotation Time Adjustment Range

Size	Allowable kinetic energy (J)	Stable operational rotation time adjustment range (s/90°)
10	0.007	
20	0.025	1 to 5
30	0.048	1 105
50	0.081	

Note) If operated where the kinetic energy exceeds the allowable value, this may cause damage to the internal parts and result in product failure. Please pay special attention to the kinetic energy levels when designing, adjusting and during operation to avoid exceeding the allowable limit.

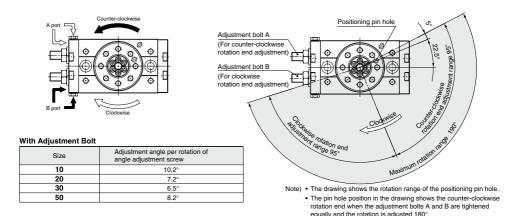
### Weight

				(g)
Size	10	20	30	50
Basic	500	940	1230	1990

<sup>\*</sup> Not including the weight of auto switch.

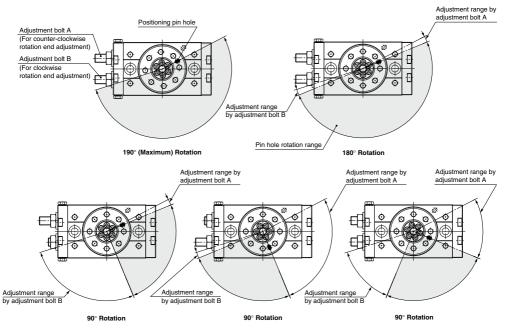
### **Rotation Direction and Rotation Angle**

- The rotary table turns in the clockwise direction when the A port is pressurized, and in the counter-clockwise direction when the B port is pressurized.
- By adjusting the adjustment bolt, the rotation end can be set within the range shown in the drawing for the desired rotation angle.



### **Rotation Angle Range Example**

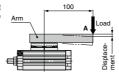
Various rotation ranges are possible as shown in the drawings below using adjustment bolts A and B.
 (The drawings also show the rotation ranges of the positioning pin hole.)



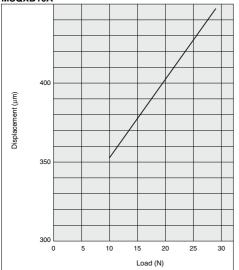
# **MSQX** Series

### Table Displacement (Reference values)

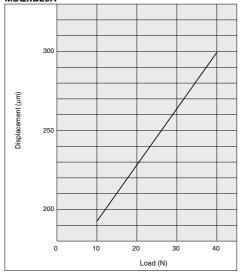
 The following graphs show the displacement at point A, which is 100 mm apart from the center of rotation, where the load is applied.



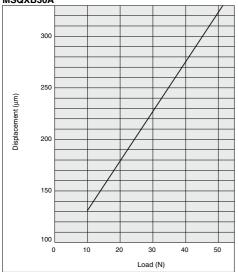
### MSQXB10A



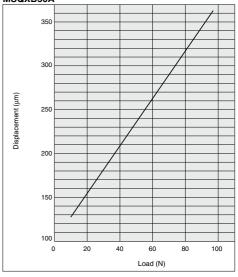
### MSQXB20A



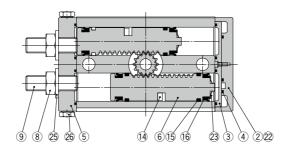
### MSQXB30A

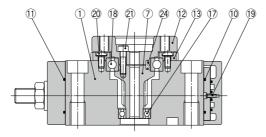


### MSQXB50A



### Construction





**Component Parts** 

No.	Description	Material
1	Body	Aluminum alloy
2	Cover	Aluminum alloy
3	Plate	Aluminum alloy
4	Seal	NBR
5	End cover	Aluminum alloy
6	Piston	Stainless steel
7	Pinion	Chrome molybdenum steel
8	Hexagon small nut	Steel wire
9	Adjustment bolt	Chrome molybdenum steel
10	Gasket	NBR
11	Gasket	NBR
12	Table	Aluminum alloy
13	Bearing retainer	Aluminum alloy
14	Magnet	_
* Indiv	idual part cannot be shipped.	

**Component Parts** 

No.	Description		Material
15	Wear ring		Resin
16	Piston seal		NBR
17	Bearing		Bearing steel
18	Bearing		Bearing steel
19	Cross recessed screw N	o. 0	Steel wire
20	Cross recessed screw	Size: 10	Stainless steel
20	Hexagon this socket head bolt	Size: 20 to 50	Chrome molybdenum steel
21	Hexagon socket head ca	p screw	Stainless steel
22	Hexagon socket head ca	p screw	Stainless steel
23	Push nut		Stainless steel
24	Parallel pin		Carbon steel
25	Seal washer		NBR
26	Plug		Steel wire

**Replacement Parts** 

Description						Par	t no.						
Description		10			20			30			50		
Seal kit		P523010-20			P523020-20			P523030-20		P523040-20			
	No.	Description	Qty.	No.	Description	Qty.	No.	Description	Qty.	No.	Description	Qty.	
	4	Seal	1	4	Seal	1	4	Seal	1	4	Seal	1	
Parts included	10	Gasket	1	10	Gasket	1	10	Gasket	1	10	Gasket	1	
in seal kit	11	Gasket	1	11	Gasket	1	11	Gasket	1	11	Gasket	1	
	15	Wear ring	4	15	Wear ring	4	15	Wear ring	4	15	Wear ring	4	
	16	Piston seal	4	16	Piston seal	4	16	Piston seal	4	16	Piston seal	4	
	25	Seal washer	2	25	Seal washer	2	25	Seal washer	2	25	Seal washer	2	



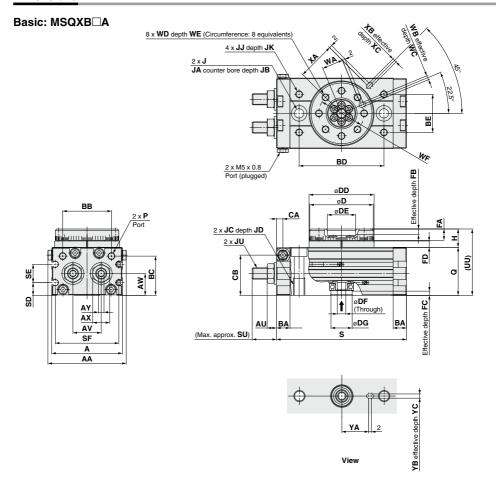
<sup>\*</sup> A set includes all parts above.

A grease pack (10 g) is included. When only a grease pack is needed, order with the following part number.

Replacement parts/Grease pack part no: P523010-21 (10 g)

# **MSQX** Series

### **Dimensions**

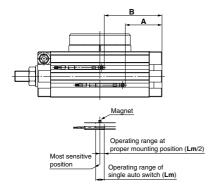


																											(mm)
Size	AA	Α	AU	ΑV	AW	AX	AY	BA	BB	вс	BD	BE	CA	СВ	D	DD	DE	DF	DG	FA	FB	FC	FD	Н	J	JA	JB
10	55.4	50	6.6	20	15.5	12	4	9.5	34.5	27.8	60	27	4.5	28.5	45h9	46h9	20H9	6	15H9	8	4	3	4.5	13	6.8	11	6.5
20	70.8	65	7.6	27.5	16	14	5	12	46	30	76	34	6	30.5	60h9	61h9	28H9	9	17H9	10	6	2.5	6.5	17	8.6	14	8.5
30	75.4	70	7.6	29	18.5	14	5	12	50	32	84	37	6.5	33.5	65h9	67h9	32H9	12	22H9	10	4.5	3	6.5	17	8.6	14	8.5
50	85.4	80	10	38	22	19	6	15.5	63	37.5	100	50	10	37.5	75h9	77h9	35H9	13	26H9	12	5	3	7.5	20	10.5	18	10.5

																									(mm)
Size	JC	JD	JJ	JK	JU	Р	Q	s	SD	SE	SF	SU	UU	WA	WB	wc	WD	WE	WF	ΧA	ХВ	хс	YΑ	ΥB	YC
10	M 8 x 1.25	12	M5 x 0.8	7	M 8 x 1	M5 x 0.8	34	92	9	13	45	17.7	47	15	3H9	3.5	M5 x 0.8	8	32	27	3H9	3.5	19	3H9	3.5
20	M10 x 1.5	15	M6 x 1	8	M10 x 1	M5 x 0.8	37	117	10	12	60	25	54	20.5	4H9	4.5	M6 x 1	10	43	36	4H9	4.5	24	4H9	4.5
30	M10 x 1.5	15	M6 x 1	8	M10 x 1	Rc 1/8**	40	127	11.5	14	65	25	57	23	4H9	4.5	M6 x 1	10	48	39	4H9	4.5	28	4H9	4.5
50	M12 x 1.75	18	M8 x 1.25	8	M14 x 1.5	Rc 1/8**	46	152	14.5	15	75	31.4	66	26.5	5H9	5.5	M8 x 1.25	12	55	45	5H9	5.5	33	5H9	5.5

<sup>\*\*</sup> In addition to Rc 1/8, G 1/8, NPT 1/8 and NPTF 1/8 are also available.

### Auto Switch Proper Mounting Position (at Rotation End Detection)



	Botation			Reed switch			Sol	id state switch	1
Size	angle	A	В	Operating angle (θ <b>m</b> )	Hysteresis angle	Α	В	Operating angle (θ m)	Hysteresis angle
10	190°	27	45	90°	10°	31	49	42°	10°
20	190°	35	62	80°	10°	39	66	35°	10°
30	190°	39	68	65°	10°	43	72	30°	10°
50	190°	49	83	50°	10°	53	87	24°	10°

Operating angle  $\theta$ m: Value of the operating range of single auto switch (Lm) as represented by rotation angle for shaft Hysteresis angle: Value of the auto switch hysteresis as represented by angle

Note) Since the above values are only provided as a guideline, they are not guaranteed. In the actual setting, adjust them after confirming the auto switch operating condition.

**SMC** 

### **MSQX** Series

# **Made to Order Specifications:**

Please contact SMC for detailed specifications, lead times and prices.

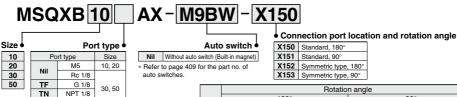


Symbol

### With External Stopper

X150/X151/X152/X153 Prevent holding torque from being halved at the rotation end

### **How to Order**



### **Specifications**

TT

Size	10	20	30	50
Rotation angle		90°,	180°	
Angle adjustment range	E	ach rotat	ion end	3° 5°

<sup>\*</sup> Specifications other than the above are the same as standard.

NPTF 1/8

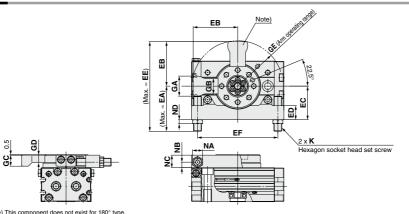
### Weight

				(g)
Size	10	20	30	50
90° spec.	600	1150	1460	2390
180° spec.	570	1090	1390	2280
	Providence of			

Values not including the auto switch weight

### Rotation angle 180° 90° X150: Standard, 180° X151: Standard, 90° bort port Standard Connection Connection port location X152: Symmetric type, 180° X153: Symmetric type, 90° Symmetric type Connection port Connection port

### **Dimensions**



Note) This component does not exist for 180° type.

		,					71									(mm)
Size	EA	EB	EC	ED	EE	EF	GA	GB	GC	GD	GE	K	NA	NB	NC	ND
10	47.1	44.3	33.5	14	91.4	80	20	15.6	11	7.5	45.2	M8 x 1	10	5.5	12.5	4
20	57.1	55.3	43	18	112.4	100	25	19.5	14	9.5	56.4	M10 x 1	14	8	16.5	4
30	58.4	60.3	46	19.5	118.7	110	27	21.5	14	9.5	61.5	M10 x 1	14	8	16.5	4
50	74.4	71.4	56	22	145.8	130	32	28	18	11.5	72.9	M14 x 1.5	19	8.5	19.5	6

<sup>\*</sup> Dimensions other than the above are the same as standard.



# CRQ2X/MSQX Series Specific Product Precautions

Be sure to read this before handling the products.

For safety instructions as well as rotary actuator and auto switch precautions, refer to the "Handling Precautions for SMC Products" and the "Operation Manual" of each product on the SMC website: https://www.smcworld.com

### Selection

## **⚠** Caution

- Changes in speed occur in applications in which there are changes to the load during operation, such as the load being lifted (lowered) against gravity.
- 2. The purpose of this product is stable rotation at low-speed.
  - It does not provide any function to cushion the impact at the operation start or end.
- Speed may vary at the rotation end depending on operating conditions. (This phenomenon can be avoided by using the external stopper.)

